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(54) **Apparatus for applying and adjusting an anchoring device**

Vorrichtung zum Anbringen und Einstellen einer Verankerungsvorrichtung

Dispositif pour appliquer et pour positionner un dispositif d'ancrage

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## Description

### BACKGROUND OF THE INVENTION

#### 1. Field of the Invention

**[0001]** The present invention relates to an apparatus for applying and adjusting a sutured anchoring device. More particularly, this invention relates to an apparatus for elevating the urethrovesical junction relative to the bladder to correct female urinary stress incontinence. US-A-4235238 discloses apparatus which includes the technical features of the pre-characterising part of claim 1 below.

#### 2. Description of Related Art

**[0002]** In females, incontinence, or the inability to control the outflow of urine, can have a variety of causes in the urinary system including congenital defects and defects from trauma or disease. The most common cause of female incontinence is known as stress incontinence and results from weakness or relaxation of the urethral sphincter.

**[0003]** Many procedures, several involving urethrovesical elevation, have been devised over the years, to cure urinary stress incontinence. One early procedure involved fixation of the urethrovesical junction to the symphysis pubis by placing sutures through part of the urethral wall, but caused urethral distortion. A modified version of the procedure involved suturing the urethral lumen directly to the symphysis pubis, and placing additional sutures through the bladder. This technique however, often led to urine loss and/or the formation of bladder stones.

**[0004]** An alternative approach involved attaching the urethrovesical junction to the narrow band of strong aponeurotic fibers which extends laterally along the pectineal line of the pubis commonly referred to as Cooper's ligament. In this procedure which is described in U.S. Pat. No. 5,149,329 to Richardson, the urethrovesical junction is elevated by bringing the paravaginal fascia into juxtaposition with Cooper's ligament through suture placement.

**[0005]** A number of procedures for urethrovesical elevation involve anchoring the paravaginal fascia to the abdominal wall. See, for example, U.S. Patent No. 5,112,344 to Petros which describes looping a filamentary element between the vaginal wall and the rectus abdominis in the anterior wall of the abdomen whereby it passes to each side of the urethra to correct the spacial relationship to the pubis. U.S. Patent No. 5,019,032 to Robertson describes a method of treatment involving the installation of sutures between the rectus fascia and the vagina by means of a needle inserted through the abdomen.

**[0006]** A sling procedure is disclosed in U.S. Patent No. 5,013,292 to Lemay and describes a method for cor-

recting female urinary incontinence by implanting a sling-like anchoring device in the skin above the symphysis pubis to adjust the urethrovesical angle. The anchoring device includes a pair of implants each having a head portion adapted to rest on the symphysis pubis and a suture portion connected to the head portion. The head portion is shaped as a figure eight having a central crossbar about which a central portion of the suture is wrapped. Utilizing a bendable needle inserted through the vaginal mucosa, the head portion of each implant is embedded in the skin over the symphysis pubis and the sutures are tied together to support the urethrovesical junction. Alternatively, the ends of the sutures can be tied to a saddle member configured to support the bladder neck.

**[0007]** Such invasive surgical procedures have also been utilized in other areas of the body, including surgery on the gall bladder, appendix, lungs and the like. For the reasons previously stated, the use of laparoscopic and endoscopic surgical procedures have been relatively popular and such popularity has provided additional incentive to develop the procedures further.

**[0008]** In laparoscopic procedures, surgery is performed in the interior of the abdomen through a small incision e.g., through narrow tubes inserted through small entrance wounds in the skin; and in endoscopic procedures, surgery is performed in any hollow viscus of the body. Laparoscopic and endoscopic procedures generally require that any instrumentation inserted into the body be sealed, i.e., provisions must be made to ensure that gases do not enter or exit the body through the laparoscopic or endoscopic incision as, for example, in surgical procedures in which the surgical region is insufflated. Moreover, laparoscopic and endoscopic procedures often require the surgeon to act on organs, tissues and vessels far removed from the incision, thereby requiring that any instruments used in such procedures be long and narrow while being functionally controllable from one end of the instrument, i.e., the proximal end.

**[0009]** Up to the present there remains a need for an apparatus which is particularly adapted to endoscopically apply sutured anchors to body tissue in a manner to positively secure the sutured anchor to the body tissue without the risk of separation. There is also a need in the surgical arts for an improved apparatus to elevate and/or restrain internal organs or structures. In particular, there remains a need to achieve urethrovesical elevation. The present invention relates to such a sutured anchor member, an apparatus for applying the sutured anchor member in a method for attaching and adjusting a sutured anchor member particularly configured and adapted to accomplish these objectives.

### SUMMARY OF THE INVENTION

**[0010]** Apparatus in accordance with the present invention is defined in the claims below.

**[0011]** An apparatus for applying an anchoring device

to body tissue comprises a handle portion defining a longitudinal axis, an elongated needle body extending from the handle portion and defining an axial bore configured to retain the anchors of the anchoring device, an elongated housing mounted adjacent the needle body and longitudinally movable with respect thereto between a first position wherein a distal end portion of the needle body is extended from the housing and a second position wherein the distal end portion of the needle body is shielded by the housing. The apparatus also includes means operatively associated with the handle portion for individually advancing the anchors from the distal end portion of the needle body. Preferably, the means for individually advancing the anchors from the needle body comprises an axially advanceable ratchet assembly which includes an elongated rack member, engaging means for locking the rack member in a predetermined axial position, a selectively actuatable driving arm configured to interact with the rack member to advance the rack member in a distal direction, and a push rod extending within the needle body and from a distal end of the rack member for advancing the anchors therefrom.

**[0012]** A preferred embodiment of anchor applying device of the subject invention may include an articulated distal end portion configured for pivotal movement relative to the elongated body of the apparatus to widen the range of operability of the instrument. To further widen the operational range of the surgical apparatus of the subject invention, the articulated distal end portion may be configured to rotate independently about a longitudinal axis extending therethrough relative to the elongated body of the instrument.

**[0013]** In a preferred embodiment of the subject invention, the anchoring device comprises an elongated suture having an anchor positioned at each end thereof, and means provided on the suture and movable with respect thereto for adjusting the operative length of the suture. Preferably, each anchor is positioned orthogonal to the elongation of the suture. The operative length of the suture is preferably adjusted by a cinching member positioned proximate a medial portion of the suture and formed by a housing having a passageway extending therethrough for receiving a looped portion of the suture. Gripping means is operatively associated with the passageway for controlling movement of the cinching member with respect to the suture in a first direction and inhibiting movement of the cinching member with respect to the suture in a second direction. The gripping means can comprise a deflectable suture gripping plate positioned within the passageway, a translating roll bar positioned within the passageway and movable between a disengaged position and an engaged position, or a tapered wedge member disposed within the passageway and movable between a first position in which relative movement of the suture and the cinching member is permitted and a second position in which such relative movement is inhibited.

**[0014]** Also disclosed herein is an apparatus for ad-

justing the operative length of the anchoring device, and more particularly, drawing the suture relative to the cinching member preferably comprises a tubular outer housing which defines a longitudinal axis, a tubular inner shaft mounted for coaxial movement with respect to the outer housing, means for maintaining the radial alignment of the inner shaft with respect to the outer housing relative to the longitudinal axis thereof, and means positioned at a distal end portion of the inner shaft for engaging a suture. Preferably, the means for maintaining the angular orientation of the inner shaft with respect to the outer housing includes an elongated guide slot formed in the inner shaft and a transverse guide pin mounted in the outer housing for communicating with the guide slot. The means for engaging a suture preferably comprises a rigid hook member mounted at the distal end of the inner shaft.

**[0015]** A method is disclosed for correcting female urinary stress incontinence by elevating the urethrovaginal function relative to the bladder by bringing the vaginal wall into juxtaposition with Cooper's Ligament. The method comprises the steps of: providing an anchoring device including an elongated suture having a first anchor at one end thereof, a second anchor at the opposed end thereof and means for cinching the suture disposed therebetween; securing the first anchor to a first structure, e.g., the vaginal wall; securing the second anchor to a second structure, e.g., Cooper's ligament; and drawing the suture relative to the cinching means to approximate the first and second anchors. In the context of the treatment of female urinary stress incontinence, one anchor elevates the urethrovaginal junction relative to the bladder by approximating the vaginal wall with respect to Cooper's ligament.

**[0016]** Preferably, the step of securing the first anchor in the vaginal wall comprises inserting the needle through the vaginal wall, deploying an anchor, withdrawing the needle from the vaginal wall at a location spaced from the point of insertion, and subsequently emplacing the anchor exterior of the vaginal wall. The step of securing the second anchor preferably comprises extending the anchor through Cooper's ligament from a posterior surface thereof to an anterior surface thereof, and emplacing the anchor adjacent the anterior surface of Cooper's ligament. The step of drawing the suture relative to the cinching means preferably comprises engaging a loop formed in the suture adjacent the cinching member and subsequently drawing the suture loop through the cinching means to approximate the first and second anchors.

**[0017]** The method for surgically treating female urinary stress incontinence may also comprise the steps of: providing an anchor placement apparatus including a needle body defining a bore in which the first and second anchors are retained, and providing an apparatus for drawing the suture relative to the cinching member. The step of securing the first anchor to the vaginal wall is accomplished by inserting the distal end of the needle

body into the vaginal wall, extending the needle body from the vaginal wall at a location spaced from the point of insertion, and subsequently advancing the first anchor from the distal end of the needle body to emplace the anchor exterior of the vaginal wall. The second anchor is then secured to Cooper's ligament by extending the needle body through Cooper's ligament from a posterior surface thereof to an anterior surface thereof, and subsequently advancing the second anchor from the distal end of the needle body to emplace the second anchor adjacent the anterior surface of Cooper's ligament. The loop formed in the suture adjacent the cinching means is engaged with the retractable hook provided at the distal end of the suture drawing apparatus. Retracting the hook draws the suture relative to the cinching means and thereby approximates the first and second anchors to bring the vaginal wall and Cooper's ligament into juxtaposition so as to elevate the urethrovaginal junction relative to the bladder.

[0018] Although the invention has been described above primarily in the context of the treatment of female urinary stress incontinence, it may also find applicability in a variety of clinical settings where it is desired to elevate, approximate and/or restrain one or more organs or structures. Further features of the apparatus of the subject invention will become more readily apparent from the following detailed description of preferred embodiments of the invention taken in conjunction with the drawings.

#### BRIEF DESCRIPTION OF THE DRAWINGS

[0019] So that one skilled in the art to which the subject invention appertains will better understand how to make and use the invention, preferred embodiments of the method and apparatus will be described hereinbelow with reference to the drawings wherein:

Fig. 1 is a perspective view of a surgical anchoring device;

Fig. 2 is a side elevational view in partial cross-section of the cinching member of the anchoring device of Fig. 1 as the suture is moved relative thereto;

Fig. 3 is a side elevational view in partial cross-section of the cinching member of the anchoring device of Fig. 1 with the suture in a stationary position with respect thereto;

Fig. 4 is a perspective view of another anchoring device;

Fig. 5A is a side elevational view in partial cross-section of the cinching member of the anchoring device of Fig. 4 as the suture is moved relative thereto;

Fig. 5B is a side elevational view in partial cross-

section of the cinching member of the anchoring device of Fig. 4 with the suture in a stationary position with respect thereto;

Fig. 6A is a perspective view in partial cross-section of yet another anchoring device;

Fig. 6B is a top plan view in cross-section of the cinching member of the anchoring device of Fig. 6A with the wedge member thereof disposed in a position wherein relative movement of the cinching member and suture is inhibited;

Fig. 7 is a perspective view of an apparatus for applying the anchoring device illustrated in Figs. 1 and 4 during a surgical procedure;

Fig. 8 is a perspective view of the anchor applying apparatus of Fig. 7 illustrating the deployment of an anchoring device;

Fig. 9 is an exploded perspective view of the anchor applying apparatus of Fig. 7;

Fig. 10 is a side elevational view in partial cross-section of the anchor applying apparatus of Fig. 7 prior to actuation;

Fig. 11 is a side elevational view in partial cross-section of the anchor applying apparatus of Fig. 7 in a partially actuated position;

Fig. 12 is a side elevational view in partial cross-section of the anchor applying apparatus of Fig. 7 in a fully actuated position;

Fig. 13 is a side elevational view in partial cross-section of the anchor applying apparatus of Fig. 7 subsequent to actuation;

Fig. 14A is a side elevational view in cross-section of an anchor applying apparatus constructed in accordance with a preferred embodiment of the subject invention prior to actuation; Fig. 14B is a side elevational view in cross-section of the anchor applying apparatus of Fig. 14A in a fully actuated position;

Fig. 15A is a perspective view of an apparatus for adjusting the operative length of the anchoring device of Figs. 1 and 4 during a surgical procedure;

Fig. 15B is a perspective view in partial cross-section of the Fig. 15A illustrating the movement of the inner shaft relative to the outer housing thereof;

Fig. 15C is an exploded perspective view of the apparatus of Fig. 15A;

Fig. 16A is a perspective view of another anchor applying apparatus constructed in accordance with a preferred embodiment of the subject invention;

Fig. 16B is a perspective view of the distal end portion of the surgical apparatus of Fig. 16A disposed in an articulated position;

Fig. 16C is a side elevational view in cross-section of the surgical apparatus of Fig. 16A with tissue captured in the distal end thereof prior to actuation;

Fig. 16D is a side elevational view in cross-section of the surgical apparatus of Fig. 16A with the needle body advanced distally to pierce through the tissue;

Fig. 16E is a side elevational view in cross-section of the surgical apparatus of Fig. 16A with the feed rod advanced incrementally within the needle body to drive an anchor member therefrom;

Fig. 16F is an enlarged side elevational view in cross-section of the surgical apparatus of Fig. 16A with the needle body disposed in a distally advanced position and the distal end portion of the frame disposed in an articulated position;

Fig. 17 is a sagittal section taken through the pelvic region of a female illustrating the anchor applying apparatus of Fig. 7 emplacing the first anchor of the anchoring device of Fig. 1 in the vaginal wall;

Fig. 18 is a sagittal section illustrating the application of the second anchor of the anchoring device of Fig. 1 in Cooper's ligament;

Fig. 19 is a sagittal section illustrating the engagement of the suture of the anchoring device of Fig. 1 by the anchor device adjusting apparatus of Fig. 15A;

Fig. 20 is a sagittal section illustrating the drawing of the suture relative to the cinching member by the anchor device adjusting apparatus of Fig. 15A to move the vaginal wall and Cooper's ligament into juxtaposition;

Fig. 21 is a sagittal section illustrating the urethrovesical junction elevated relative to the bladder as a result of the approximation of the first and second anchors with respect to one another; and

Fig. 22 is a plan view of an enclosure or kit containing the anchor applying apparatus of Fig. 7 and the anchor device adjusting apparatus of Fig. 15A.

## DETAILED DESCRIPTION OF THE PREFERRED EMBODIMENTS

[0020] In the drawings and in the description which follows, the term "proximal", as is traditional, will refer to the end of the apparatus which is closest to the operator, while the term "distal" will refer to the end which is furthest from the operator.

### I. OVERVIEW OF THE SUBJECT INVENTION

[0021] The overall objective of the apparatus of the subject invention is to apply a pair of sutured anchors to a body organ or structure and adjust the relative positions of the two structures through which the sutured anchors have been placed. More particularly, the apparatus of the present invention may be used to elevate, approximate and/or restrain one or more organs or structures and is especially applicable to suspending the neck of the bladder by elevating the urethrovesical junction relative to the bladder. Referring in general to the figures, to more easily facilitate the method, the subject invention may include three devices for performing this procedure: an adjustable anchoring device 10, an apparatus for applying the anchoring device to body tissue 200, and an apparatus for adjusting the length of the anchoring device after it has been emplaced 300. The following is a brief description of each of the three devices and the manner in which each is employed, although other devices may be substituted for or used in combination with these devices to perform the application of and/or approximation of the anchoring device. A detailed description of each device and the method of elevating an exemplary structure, namely the urethrovesical junction relative to a bladder, will follow thereafter.

[0022] Briefly, the adjustable anchoring device 10 comprises an elongated suture having a rigid anchor disposed at each end thereof, and a cinching member 20 associated therewith and which is configured to prevent movement of the suture to adjust the operative length thereof. The apparatus 200 for applying the anchoring device 10 includes a handle portion from which extends an elongated needle body configured to retain the anchors, and a ratcheting mechanism for individually advancing the anchors from the needle body. The apparatus 300 for adjusting the operative length of the anchoring device 10 comprises a telescoping tubular assembly having a retractable hook associated therewith configured to engage a looped portion of the suture disposed adjacent the cinching member. Operation of the apparatus will effect relative movement of the suture and cinching member to vary the length of the suture and thereby approximate the ends thereof.

### II. THE ANCHORING DEVICE

[0023] Referring to Figs. 1-3, an anchoring device

useful with a preferred embodiment of the subject invention is illustrated and is designated generally by reference numeral 10. The anchoring device 10 includes an elongated suture 12 having a first anchor 14 at one end thereof and a second anchor 16 at the opposed end thereof. Anchors 14 and 16 are preferably substantially orthogonal to the elongation of suture 12, and are formed of a bio-compatible material. The material preferably is formed of titanium, but may also be a rigid plastic or stainless steel. Preferably, anchors 14 and 16 are formed with internal bores 14a and 16a, respectively, for receiving and retaining the end portions of suture 12, as illustrated in Fig. 1. However, the anchors may be insert molded or fastened to the ends of the suture by other methods known in the art, such as, for example, adhesive bonding or sonic welding. Alternatively, the anchors may be integrally formed with the suture portion of the device.

[0024] A cinching member 20 is positioned on suture 12 between anchors 14 and 16 for adjusting the operational length of the suture 12, and more particularly, for facilitating approximation of the anchors 14 and 16 provided at each end thereof. As best shown in Fig. 2, the cinching member 20 has a stepped axial passageway 22 defining a leading section 24 and a trailing section 26. The leading section 24 has a diameter which is less than that of the trailing section 26. Transverse buttressing walls are formed within passageway 22 and include a forward wall 28 and a rearward wall 30. A transverse slot 35 is formed in the housing wall 32 of cinching member 20, in line with the rearward wall 30, for receiving and retaining a deflectable gripping plate 34. The gripping plate 34 operatively separates the leading section 24 and the trailing section 26 of passageway 22. Furthermore, the relative orientation of the forward wall 28 with respect to the rearward wall 30 creates a gap between the free edge 36 of gripping plate 34 and the internal edge 38 of forward wall 28. This gap permits the extension of suture 12 through passageway 22.

[0025] In operation, the application of a tensile force on, or linear movement of, suture 12 in the direction indicated by arrow "A" in Fig. 2, will cause the gripping plate 34 to deflect away from the forward buttressing wall 28, enlarging the gap therebetween, and permitting substantially unobstructed movement of suture 12 in direction "A" relative to the stationary cinching member 20. In contrast, in the absence of an applied force along the length of suture 12, as shown for example in Fig. 3, the gripping plate 34 will remain parallel with the forward buttressing wall 28 and the gap therebetween will be at a minimum, thereby inhibiting movement of suture 12 relative to cinching member 20.

[0026] Preferably, as illustrated in Fig. 1, the cinching member 20 is initially positioned at the mid section of suture 12 in such a manner so that a loop 40 is formed in suture 12 adjacent the trailing section 26 of passageway 22. In use, as the suture loop 40 is drawn relative to the cinching member 20, the anchors 14 and 16 po-

sitioned at the opposed ends of suture 12 will approximate toward one another, thereby curtailing the operative length of the suture 12.

[0027] Referring to Figs. 4-5B, another cinching member is illustrated and is designated generally by reference numeral 100. Cinching member 100 comprises a housing 102 having opposed parallel side walls 104 and 106 and converging upper and lower bearing walls 108 and 110. A passageway 112 extends through the housing 102 from an inlet port 116 to an outlet port 114. The outlet port 114 defines an aperture which is smaller than the aperture defined by the inlet port 116. An elongated slot 118 is defined in the internal surface of side wall 104 and a corresponding slot (not shown) is formed in the internal surface of side wall 106. The slots are configured to retain the axle pin 122 of a transverse roller bearing 126.

[0028] Roller bearing 126 is dimensioned to have suture 12 wrapped thereabout in such a manner so as to create looped portion 40 adjacent the inlet port 116, as best seen in Fig. 4. In use, the roller bearing 126 is movable between a non-engaging position adjacent the inlet port 116 (see Fig. 5A), and an engaging position adjacent the outlet port 114, wherein the roller bearing 126 compresses the suture 12 against the bearing walls 108 and 110 of housing 102 to secure the position of cinching member 100 with respect to the suture 12 (see Fig. 5B). To adjust the length of suture 12 and thereby approximate the opposed ends thereof, the looped portion 40 of suture 12 is drawn through passage 112 until a desired operative suture length is achieved. During this suture adjustment period, the roller bearing is maintained in its engaging position and rotates to accommodate the movement of suture 12 relative thereto.

[0029] Referring to Figs. 6A and 6B, another cinching member is illustrated and is designated generally by reference numeral 150. Cinching member 150 comprises a housing 152 of generally rectangular configuration having opposed side walls 154 and 156 and opposed upper and lower walls 158 and 160. A passageway 162 extends through the housing 152 from an inlet port 164 to an outlet port 166. The inlet port 164 is substantially rectangular in cross-sectional configuration while the outlet port 166 is defined by outwardly diverging walls. A divider 168 is formed at the geometric center of the outlet port 166 to separate the suture portions 12a and 12b which extend therethrough. An elongated track 172 is formed in the upper wall 158 of housing 152 for cooperating with wedge member 175 to limit the movement thereof within the passageway 162. The interior region 170 of passageway 162 is tapered inwardly toward the outlet port 166.

[0030] Wedge member 175 defines a tapered body 176 dimensioned and configured to translate within the interior region 170 of passageway 162. Opposed sloping ribbed surfaces 178 and 180 are defined on the body 176 of wedge member 175 to frictionally engage the suture portions 12a and 12b as they extend through the

passageway 162. A protuberance 182 extends from the body 176 of wedge member 175 for cooperative engagement with the elongated track 172 formed in the upper wall 158 of housing 152.

[0031] In operation, the wedge member 175 is movable within passageway 162 between a first position, wherein movement of the suture 12 through the passageway 162 is permitted, and a second position, illustrated in Fig. 6B, wherein movement of the suture 12 through the passageway 162 is inhibited as the ribbed surfaces 178 and 180 frictionally engage the suture 12 and compress suture portions 12a and 12b against interior region 170 of passageway 162.

[0032] It will be readily apparent to those skilled in the art to which the subject invention appertains that other mechanisms for cinching the suture may otherwise be provided.

### III. APPARATUS FOR APPLYING THE ANCHORING DEVICE

[0033] Referring to Figs. 7-13, a surgical apparatus for applying the anchoring device 10 is illustrated and is designated generally by reference numeral 200. In brief, surgical apparatus 200 comprises a handle portion 202, an elongated needle body 204 extending from the handle portion 202 and configured to retain anchors 14 and 16, a sheath 206 mounted adjacent needle body 204 and configured to move longitudinally with respect thereto. An actuation mechanism designated generally by reference numeral 208 is operatively associated with the handle portion 202 for effectuating the individual advancement of anchors 14 and 16 from the needle body 204, as illustrated, for example, in Fig. 8.

[0034] Turning to Fig. 9, the handle portion 202 of surgical apparatus 200 includes hemi-sections 210 and 212 adapted to be mounted to one another and defining a compartmented axial bore 214 configured to accommodate various elements associated with actuation mechanism 208. The actuation mechanism 208 includes a plunger 216 dimensioned for retention within the proximal compression chamber 218 of axial bore 214. A coiled return spring 220 is coaxially disposed about plunger 216 and is positioned against the distal wall 222 of chamber 218 for biasing the plunger 216 in a proximal direction. A cylindrical drive shaft 224 extends from the distal end of plunger 216 and is accommodated within a primary drive chamber 226 of axial bore 214.

[0035] Drive shaft 224 communicates with a segmented ratchet shaft 228 which is operatively disposed within a secondary drive chamber 230 of axial bore 214. Ratchet shaft 228 is defined by a plurality of ratchet segments 228a-228f each of similar configuration. The ratchet segments 228a-228f are also of equal length and the length of each corresponds to the length of each of the anchors retained within needle body 204. Thus, as each segment of ratchet shaft 228 is advanced a dis-

tance equal to its length, so to are the anchor members disposed within the needle body 204. See generally, Figs. 10-13.

[0036] With continuing reference to Fig. 9, the actuation mechanism 208 further comprises an elongated drive arm 232 which extends from the drive shaft 224 and which includes an angularly depending distal portion 234 configured to selectively engage the segmented ratchet shaft 228 and drive it in a distal direction in response to movement of plunger member 216. The distance of the compression stroke of plunger 216 also corresponds to the length of each segment of ratchet shaft 228. A locking beam 236 resides in a cavity 238 adjacent the distal end of the secondary drive chamber 230 for securing the axial position of the ratchet shaft 228 following each incremental movement thereof. The locking beam 236 comprises a deflectable leaf spring which is normally biased into a position of engagement with ratchet shaft 228. A guide ring 240 is retained within an annular chamber 242 adjacent the secondary drive chamber 230 to ensure the stability of ratchet shaft 228 during its distal translation.

[0037] An elongated push rod 244 extends from the distalmost segment 228f of ratchet shaft 228 and is dimensioned and configured to translate through the axial bore 246 of needle body 204. Push rod 244 is positioned within an axial extension shaft 246 which depends from handle portion 202 and which is retained therein by mounting pins 248 and 250. Extension shaft 246 includes an elongated guide channel 252 through which push rod 244 translates, an internal chamber 254 for retaining the cinching member 20 of anchoring device 10, and a distal reception port 256 for mounting the proximal end 258 of needle body 204. The distal end portion 260 of needle body 204 depends angularly from the elongation thereof and defines a piercing point configured to extend through body tissue.

[0038] The sheath 206 is mounted coaxially with extension shaft 246 and is movable with respect thereto between a plurality of longitudinal positions to selectively expose the distal end portion 260 of needle body 204. A manipulation knob 262 (262a, 262b) is positioned adjacent the proximal end 264 of extension shaft 246 to position the sheath along the needle body 204. A transverse control pin 266 extends from manipulation knob 262, through an aperture 268 adjacent the proximal end 264 of sheath 206 to communicate with a guide track 270 defined in the outer wall 272 of extension shaft 246. Guide track 270 includes an elongated primary section 274 and a plurality of depending recessed areas 276a-276g within which control pin 266 may be selectively positioned to orient the sheath 206 in a desired longitudinal position.

[0039] In use, the sheath 206 may be moved relative to the extension shaft 246 by rotating the knob 262 relative to the longitudinal axis defined thereby to position control pin 266 within the primary section 274 of guide track 270. Thereupon, the sheath 206 may be moved

along the length of the guide track 270 until a desired location is achieved, and then, the sheath 206 may be rotated to position the control pin 266 in a selected recessed area 276. When control pin 266 is positioned within the proximal most recessed area 276a, the distal portion 260 of needle body 204 is fully exposed by the sheath 206 (see Fig. 8). Conversely, when control pin 266 is positioned within the distal most recessed area 276g, the distal portion 260 of needle body 204 is fully shielded by sheath 206 (see Fig. 7).

[0040] Referring now to Figs. 10-13, there is illustrated a series of operational views of the surgical apparatus 200. In Fig. 13, the distal most ratchet segment 228f has been advanced by drive arm 232 and the first anchor 14 has been advanced from the distal end portion 260 of needle body 204. To deploy the second anchor 16 from the needle body 204, plunger 216 is moved in a distal direction against the bias of return spring 220 so as to urge drive shaft 224 forward within primary drive chamber 226, as shown in Fig. 11. As a consequence, drive arm 232, which is engaged behind ratchet segment 228e, urges ratchet shaft 228 in a distal direction through a distance which is equal to the length of segment 228e. Concomitantly, the push rod 244 advances distally, driving anchor 16 from the distal end portion 260 of needle body 204, as shown in Fig. 12. Subsequently, coiled spring 220 decompresses to return plunger 216 to a neutral position and position the distal end of drive arm 232 behind ratchet segment 228d. At such a time, locking beam 236 interacts with ratchet segment 228d to maintain its axial position.

[0041] Referring to Figs 14A and 14B, there is illustrated another embodiment of a surgical apparatus for applying the anchoring device 10, which apparatus is designated generally by reference numeral 280. Surgical apparatus 280 includes a handle portion 281 defining an internal cavity 282 dimensioned to house a two-stage actuation mechanism 283. The actuation mechanism 283 is configured to move an elongated needle body 284 relative to a sheath 285 and subsequently advance a push rod 286 through the needle body 284 to individually drive anchors 14 therefrom. The actuation mechanism 283 includes a spring biased plunger 287 which translates within a chamber 288 formed in an internal actuation sleeve 289 which is configured to translate within the cavity 282 defined in handle portion 281. A linear ratchet assembly 290 which is substantially similar to that which is provided in surgical apparatus 200 is operatively associated with the internal actuation sleeve 289 and the plunger 287. The proximal end of needle body 284 extends from a guide tube 291 which is connected to the tapered end portion 292 of actuation sleeve 289, and the proximal end of push rod 285 extends from the distal end 290a of ratchet assembly 290.

[0042] In operation, partial compression of plunger 287 will cause corresponding distal movement of the needle body 284 relative to sheath 285 to penetrate through body tissue disposed within the tissue reception

port 293 defined in sheath 285. The needle body 284 will continue to advance distally until the tapered end portion 292 of actuation sleeve 289 abuts against the forward buttressing wall 294 of cavity 282, as illustrated in Fig. 14B. At such a time, continued movement of plunger 287 will cause the linear ratchet mechanism 290 to advance distally relative to actuation sleeve 289. As a result, the push rod 285 will advance through the needle body 284 to urge the distalmost anchor member 14 therefrom. Subsequently, the plunger 287 will return to the prefired position illustrated in Fig. 14A.

[0043] Referring to Fig. 16A, another surgical apparatus for applying anchoring devices (i.e. the suture and cinching members shown in either Figs. 1, 4, or 6A) is illustrated and is designated generally by reference numeral 600. In brief, surgical apparatus 600 comprises a handle assembly 612 which houses an actuation assembly 614, and an elongated frame 616 which houses an elongated reciprocating flexible needle body 618. The actuation assembly 614 is configured to effectuate the initial longitudinal movement of the needle body 618 through the frame 616, and the subsequent advancement of an anchor member from the distal end of the needle body 618 (see generally Fig. 16E).

[0044] As best seen in Fig. 16B, the frame 616 of surgical apparatus 600 further comprises an articulating distal end portion 620 which is pivotally connected to body portion 622 by a pivot pin 621 and which is configured to pivot relative to the body portion 622 of frame 616 (i.e., about the y-axis). The distal end portion 620 of frame 616 is defined by a base portion 624 and a sleeve portion 626. A reception port 628 is formed in the sleeve portion 626 for receiving the tissue to be anchored (see generally Fig. 16C). The sleeve portion 628 is configured to rotate independently about a longitudinal axis extending therethrough relative to the base portion 624 (i.e., about the z-axis). This unique construction serves to increase the range of operability of surgical apparatus 600 during an endoscopic or laparoscopic procedure.

[0045] Referring now to Figs. 16C-16E, the handle assembly 612 of surgical apparatus 600 includes an elongated housing 630 of substantially rectangular configuration which defines an internal actuation chamber 632 for housing the actuation assembly 614. The actuation assembly 614 includes a plunger 634 having a proximal user engagement portion 636, an elongated shaft portion 638 which extends through the proximal wall 640 of housing 630 and includes an intermediate compression flange 641, and a distal drive portion 642. The compression flange 641 and the distal drive portion 642 of plunger 634 are operatively associated with a carrier assembly 644.

[0046] The carrier assembly 644 is configured to translate longitudinally within the actuation chamber 632 of housing 630 and is biased proximally within the actuation chamber 632 by opposed compression springs 646a and 646b. The carrier assembly 644 de-



finer primary and secondary internal actuation chambers 648a and 648b, respectively. The compression flange 641 of plunger 634 is accommodated within the primary chamber 648a of carrier assembly 644 and is biased proximally therein by opposed compression springs 650a and 650b. The distal drive portion 642 of plunger 634 is accommodated within the secondary chamber 648b of carrier assembly 644.

[0047] The proximal end 618a of the flexible needle body 618 is mounted in a bushing 652 which is secured in the distal wall 644a of carrier assembly 644. An elongated feed rod 654 which is disposed in a channel 638a formed in the shaft portion 638 of plunger 634 extends from the distal drive portion 642 of plunger 634, through the secondary chamber 648b of carrier assembly 644, and into the axial bore 618b of needle body 618. Feed rod 654 is an elongated rod dimensioned and configured for coaxial movement relative to the flexible needle body 618 and includes a series of circumferential grooves 654a which are sequentially spaced along the outer periphery thereof. The spacing of these grooves 654a correspond substantially to the length of anchor member 14. The grooves 654a are configured to interact with a spring biased clutch plate 656 having an aperture 656a through which the feed rod 654 extends.

[0048] Clutch plate 656 is operatively disposed within a cavity 642a formed in the drive portion 642 of plunger 634 and is biased into a rod engaging position by a leaf spring 657. The clutch plate 656 functions to permit the incremental distal movement of the feed rod 654 relative to the needle body 618 while inhibiting such movement in a proximal direction. A pivoting latch member 658 is mounted to the carrier assembly 644 for inhibiting the relative movement of the plunger 634 and the carrier assembly 644 until such time as the carrier assembly has been advanced to the proximal wall 632a of actuation chamber 632.

[0049] In use, during a surgical procedure, a first portion of body tissue is gathered within the reception port 628, as illustrated in Fig. 16C. Thereafter, distal movement of the plunger 634 will initially cause the carrier assembly 644 to translate distally within actuation chamber 632 against the bias of compression springs 646a and 646b. Subsequently, as illustrated in Fig. 16D, the needle body 618 will advance through frame 616 to pierce through the body tissue disposed within reception port 628. The carrier assembly 644 will continue to travel distally until the distal wall 644a thereof abuts against the proximal wall 632a of actuation chamber 632. Thereupon, the latch member 658 will pivot into a cavity 659 which is formed in the housing 630 to permit the relative movement of the plunger 634 within the carrier assembly 644. Continued distal movement of the plunger 634 within carrier assembly 644 against the bias of compression springs 650a and 650b will incrementally advance the feed rod 654 distally within the axial bore 618b of needle body 618. Consequently, the distal-most anchor member 14 of the anchoring device 10 will be driven

from the distal end 618c of needle body 618b, as illustrated in Fig. 16E.

[0050] The subsequent release of plunger 634 will enable the plunger 634 to translate proximally within the carrier assembly 644 under the influence of compression springs 650a and 650b. However, clutch plate 656 will prevent the feed rod 654 from returning proximally with the plunger 634 to its prefired position. Instead, the feed rod 654 will be maintained in its fired position, advanced a distance equal to the length of the anchor member 14 which has been displaced from the needle body 618. Continued proximal translation of the plunger 634 will enable the carrier assembly 644 to return to its prefired position under the influence of springs 646a and 646b, drawing therewith the needle body 618. A second portion of body tissue is then gathered within the reception port 628 and the sequence of operation described hereinabove is repeated to deploy the second anchor member 16 of anchoring device 10, and thereby operatively connect the first and second tissue portions.

[0051] Referring to Fig. 16F, the mechanism for effectuating pivotal movement of the distal end portion 620 of frame 616 comprises a pair of spaced apart reciprocating rod members 660 and 662 which extend from a proximal control link 664 into the distal end portion 620 of frame 616. The control link 664 is pivotally mounted upon a transverse post 668 and includes opposed slots 664a and 664b for engaging the upturned proximal end portions 660a and 662a of rod members 660 and 662, respectively. A flange 670 depends from an end of control link 664 and is dimensioned and configured to operatively engage and be driven by a helical track 672 defined within an annular rotation collar 674. A support bearing 675 is disposed within the body portion 622 of frame 616 adjacent the distal end thereof for supporting the flexible needle body 618 when the distal end portion 620 of frame 616 is articulated into a desired angular position.

[0052] In use, rotation of collar 674 will cause corresponding pivotal movement of the control link 664 about post 668. In particular, clockwise rotation of link 664 about post 668 in response to rotation of collar 674 will cause rod member 660 to translate in a proximal direction while causing rod member 662 to translate in a distal direction. As a result, rod 662 will be urged against an abutment surface 624 which is defined in the base portion 624. Thereupon, the distal end portion 620 of frame 616 will be pivoted from a first position illustrated in Fig. 16E, in axial alignment with the body portion 622, to a second position illustrated in Figs. 16B and 16F, angled with respect to the longitudinal axis defined by the body portion 622 of frame 616 (i.e., rotated about the y-axis).

[0053] With continued reference to Fig. 16F, proximal section of the body portion 622. Helical drive wire 682 is operatively connected to an elongated drive shaft 686 which extends through body portion 622. The distal end of drive shaft 686 is operatively connected to a second helical drive wire 688 which is accommodated within a

helical track 692 defined within base portion 624. The distal end of drive wire 688 is mounted to the sleeve portion 626.

[0054] In use, rotation of control knob 680 in a first angular direction will cause the helical drive wire 682 to advance in a generally distal direction. As a result, the drive shaft 686 will translate distally and will cause helical drive wire 688 to travel distally within track 692. Consequently, the sleeve portion 626 will rotate with respect to the base portion 624 (i.e., about the z-axis shown in Fig. 16B). Accordingly, the user will be able to orient the tissue reception port 628 in a suitable position for engaging the target tissue. Rotation of the control knob 680 in a second opposed angular direction will effect the proximal translation of drive shaft 686 and corresponding opposed rotation of sleeve portion 626.

#### IV. APPARATUS FOR DRAWING THE SUTURE

[0055] Referring to Figs. 15A-15C, a suture drawing apparatus is illustrated and is designated generally by reference numeral 300. As best seen in Fig. 15C, apparatus 300 comprises a pair of telescopically associated members including an elongated inner control shaft 302 having a proximal end portion 304 and a distal end portion 306, and an elongated outer housing tube 308 having a proximal end portion 310 and a distal end portion 312. An axial manipulation handle 314 is positioned at the proximal end portion 304 of control shaft 302 and is mounted thereto by a pair of spaced apart set pins 316 and 318. A grasping handle 320 is provided at the proximal end portion 310 of housing tube 308 for maintaining the longitudinal position of the housing tube 308 as the inner control shaft 302 is moved with respect thereto.

[0056] An elongated guide slot 322 extends along a medial portion of control shaft 302 for communicating with a transverse guide pin 324 mounted adjacent the proximal end portion 310 of housing tube 308. The interaction of the guide slot 322 and the guide pin 324 serves to maintain the relative radial alignment of the inner control shaft 312 relative to the outer housing tube 308 with respect to the longitudinal axis defined thereby. In so doing, a suture drawn into the housing tube 308 by control shaft 302 will not become entangled.

[0057] A mounting slot 326 is formed at the distal end portion 306 of the inner control shaft 302 for receiving and retaining the shank portion 328 of an elongated grasping hook 330. The distal end 332 of grasping hook 330 depends angularly from the elongation thereof and is dimensioned and configured to engage the looped portion 40 of the suture 12 of anchoring device 10. In operation, as best seen in Fig. 15B, a suture may be drawn into the outer housing tube 308 of surgical apparatus 300 by retracting the inner control shaft 302 into the outer housing tube 308, while maintaining the longitudinal position of the outer housing tube 308 by holding grasping handle 320. The distance that the suture may be drawn into housing tube 308 will be limited by the

length of the guide slot 322 in control shaft 302.

#### V. THE URETHROVESICAL ELEVATION PROCEDURE

[0058] Referring to Figs. 17-21, a series of sagittal sections taken through the pelvic region of a female are provided which illustrate the operational steps of a method which can be performed with the apparatus of the subject invention. While the following method is directed to a method for urethrovesical elevation, it should be noted that the procedure is exemplary, and that other applications of the sutured anchor devices may be utilized in a manner to either suspend, retract, approximate or otherwise position tissue or organs relative to one another. One example of such a procedure is closure of an incision, such as fascia, which would involve placing one anchor of an anchoring device through a first side of the incision and then placing the second anchor of the suture anchoring device through the second opposed side of the incision. With the two anchors of the device adjacently emplaced, the cinching member is engaged by the apparatus for adjusting the operative length of the anchoring device. The apparatus for adjusting the operative length would engage the looped portion of the suture and effects relative movement of the suture and cinching member to vary the length of the suture and thereby approximate the ends thereof and approximate the opposed incision sides. In fascia closure, the anchoring device may also be used in conjunction with a biocompatible washer which would be applied around the suture between the anchors 14, 16 and the structure through which the anchors have been inserted to distribute the force or compression that the anchors are subjected to.

[0059] In each figure, the anatomical structures related to the subject procedure will be designated by the following numbering convention: the retropubic space 400; the vagina 402 including the vaginal wall 404 having an interior surface 406 and an exterior surface 408; the bladder 410; the urethra 412; the urethrovesical junction or the bladder neck 414; Cooper's ligament or the pectineal ligament 416 having a posterior surface 418 and an anterior surface 420; the pubic bone 422; and the abdominal wall 424 including the skin 426 and subcutaneous fat 428.

[0060] Referring now to Fig. 17, initially the anchor applying apparatus 200 is extended through the abdominal wall 424 to introduce the instrument into the retropubic space 400. The introduction can be made through a small incision or through a trocar or cannula device inserted into the abdomen. Once inside the retropubic space 400, the distal end portion of the needle body 204 is directed toward the exterior surface 408 of the vagina 402. The needle body 204 is then inserted into the vaginal wall 404 and subsequently extended from the vaginal wall 404 at a location spaced from the point of insertion. At such a time, the first anchor 14 disposed at

the end of suture 12 is advanced from the distal end of the needle body 204 and emplaced adjacent the exterior surface 408 of the vaginal wall 404, thereby securing the first anchor 14 to the vaginal wall 404.

[0061] Referring now to Fig. 18, to secure the second anchor 16 at the opposed end of suture 12 to Cooper's ligament, the anchor applying device 200 is initially directed toward Cooper's ligament 416. Then, the distal end of the needle body 204 is extended through Cooper's ligament 416 from the posterior surface 418 thereof to the anterior surface 420 thereof. Thereupon, the second anchor 16 is advanced from the distal end of the needle body 204 and emplaced adjacent the interior surface 420 of Cooper's ligament, thereby securing the second anchor 16 to Cooper's ligament. At such a time, the anchor applying apparatus 200 may be withdrawn from the retropubic space 400 through the abdominal wall 424. As apparatus 200 is withdrawn, the cinching member 20 egresses from the housing 206 and remains within the retropubic space 400.

[0062] Referring now to Fig. 19, following the removal of anchor applying apparatus 200 from the surgical site, the suture drawing apparatus 300 is introduced into the retropubic space 400 through the abdominal wall 424. The introduction will preferably occur through the same incision through which apparatus 200 was introduced. Once inside the retropubic space 400, the grasping hook 330 provided at the distal end of inner control shaft 302 is directed toward the anchoring device 10. Subsequently, the loop 40 formed in suture 12 is engaged by the distal end 332 of hook 330. Then, as illustrated in Fig. 20, the control shaft 302 is retracted into the outer housing tube 308, drawing suture 12 therewith. As suture 12 is drawn into housing tube 308, the cinching member 20 is brought into contact with the distal end thereof and is maintained thereagainst as the suture 12 is drawn relative to the cinching member 20. As a result, the first and second anchors 14 and 16 are approximated toward one another, thereby moving the vaginal wall 404 into juxtaposition with Cooper's ligament 416 so as to elevate the urethrovesical junction or bladder neck 414 relative to the bladder 410 as illustrated in Fig. 21. Once the bladder neck 414 has been elevated, the involuntary escape of urine under conditions of increased intra-abdominal pressure is effectively inhibited.

[0063] Following the initial application of the anchoring device 10, if required, additional anchoring devices may be applied to the vaginal wall and Cooper's ligament. In total, three anchoring devices are retained within the anchor applying apparatus 200 for ready application to body tissue.

## VI. THE KIT

[0064] Referring to Fig. 22, a kit containing the apparatus necessary to perform the above-described procedure is illustrated and is designated generally by reference numeral 500. The kit comprises a preformed en-

closure 510 defining recessed areas 520 and 530 for respectively retaining the apparatus 200 for applying the anchoring device 10, and the apparatus 300 for drawing the suture 12 relative to the cinching member 20. The enclosure is preferably vacuum formed from a durable plastic material and is configured to be hermetically sealed with a cover sheet 540 to maintain the sterility of the instrumentation enclosed therein.

## Claims

1. Apparatus (200) for applying a surgical anchoring device to body tissue comprising:

a) a handle assembly (202) defining a longitudinal axis; and

b) a needle body (204) extending from said handle portion, said needle body having an axial bore (214) extending therethrough for retaining said surgical anchoring device;

the apparatus being **characterised by**:

c) an elongate frame extending distally from said handle assembly and including a body portion and a distal end portion adapted for articulated movement, said distal end portion having a tissue receiving port (628) defined therein;

d) said needle body extending through said body portion, to said tissue receiving port;

e) actuation means (208) operatively associated with said handle assembly for initially moving said needle body relative to said frame to communicate with said tissue engagement port and for subsequently advancing said anchoring member from a distal end of said needle body; and

f) control means operatively associated with said frame for effectuating articulated movement of said distal end portion of said frame relative to said body portion of said frame.

2. Apparatus as claimed in claim 1, said anchoring device to be applied including an elongated suture having an anchor member positioned at each end thereof, and wherein

a) the handle assembly has an internal actuation chamber (632) formed therein for housing a reciprocating carrier assembly (644);

b) the needle body is reciprocatory and extends from said carrier assembly, and the axial bore extending therethrough is for retaining said anchor members in alignment;

c) the actuation means is for subsequently advancing one of said anchor members from a distal end of said needle body;

d) articulation control means operatively associated with said frame is provided, for effectuating articulated movement of said distal end portion of said frame relative to said body portion of said frame; and

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f) rotation control means operatively associated with said frame is provided, for effectuating rotation of said distal end portion of said frame about a longitudinal axis extending there-through relative to said body portion of said frame.

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3. Apparatus as claimed in claim 1 or 2, wherein

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a) the actuation means is configured for initially moving said needle body in a longitudinal direction relative to said elongated frame and for subsequently advancing said surgical anchoring device from a distal end of said needle body.

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4. Apparatus as claimed in any one of the preceding claims, wherein said actuation means comprises a carrier assembly configured for reciprocating movement within an actuation chamber of said housing and a plunger mechanism (634) configured for reciprocating movement relative said carrier assembly.

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5. Apparatus as claimed in Claim 4, wherein said actuation means further comprises an elongate feed rod (654) operatively connected to said plunger mechanism and extending into the axial bore of said needle body for sequentially advancing said anchor members therefrom.

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6. Apparatus as claimed in Claim 5, further comprising means for inhibiting movement of said feed rod until said plunger mechanism has moved through said first longitudinal distance.

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7. Apparatus as recited in Claim 6, wherein said inhibiting means comprises a pivoting latch member (658) connected to said carrier assembly and configured to interact with said plunger mechanism until said plunger mechanism has moved through said first longitudinal distance.

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8. Apparatus as claimed in any one of the preceding claims, further comprising means for permitting sequential advancement of said actuation means.

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9. Apparatus as claimed in any one of the preceding claims in combination with said surgical anchoring device for anchoring tissue wherein said surgical anchoring device comprises:

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a) an elongate suture (12) defining opposed

end portions;

b) a first anchor member (14) positioned at one end of said suture and a second anchor member (16) positioned at the opposed end of said suture;

c) a cinching member (20) provided on said suture between said first and second anchor members and movable with respect thereto for approximating said first and second anchor members.

10. Apparatus as claimed in claim 9, wherein said cinching member includes a housing defining a passageway for receiving at least a portion of said suture and a tapered wedge member (175) disposed within said passageway (22) and selectively movable therein for permitting relative movement of said suture and said cinching member to adjust the operative length of said suture.

11. Apparatus as claimed in Claim 9, wherein said tapered wedge member includes a plurality of outwardly extending ribs (178, 180) for engaging said suture.

12. Apparatus as claimed in claim 10 or 11, wherein said cinching member further comprises means (172, 182) for limiting relative movement of said housing and said wedge member.

13. Apparatus as claimed in in Claim 12, wherein said limiting means includes a protuberance (182) which depends from said wedge member and a track (172) defined in said housing for accommodating said protuberance.

#### Patentansprüche

1. Vorrichtung (200) zum Legen einer chirurgischen Verankerungsvorrichtung an Körpergewebe, umfassend:

a) eine Griffeinrichtung (202), die eine longitudinale Achse bestimmt; und

b) einen Nadelkörper (204), der sich von dem Griffabschnitt erstreckt, wobei der Nadelkörper eine sich durch diesen erstreckende Axialbohrung (214) aufweist zum Halten der chirurgischen Verankerungsvorrichtung; die Vorrichtung ist gekennzeichnet durch:

c) einen länglichen Rahmen, der sich in distaler Richtung von der Griffeinrichtung erstreckt und einen Körperabschnitt und einen distalen End-

abschnitt umfasst, der zur gelenkigen Bewegung angepasst ist, wobei der distale Endabschnitt eine darin bestimmte Gewebeaufnahmeöffnung (628) aufweist;

d) der Nadelkörper sich **durch** den Körperabschnitt zur Gewebeaufnahmeöffnung erstreckt;

e) ein Betätigungsmittel (208), das operativ mit der Griffereinrichtung zusammenhängt, für die anfängliche Bewegung des Nadelkörpers relativ zu dem Rahmen, um so mit der Gewebeaufnahmeöffnung in Verbindung zu stehen, und für das anschließende Vorwärtsbewegen des Verankerungselements von einem distalen Ende des Nadelkörpers; und

f) ein Kontrollmittel, das operativ mit dem Rahmen zusammenhängt, um die gelenkige Bewegung des distalen Endabschnittes des Rahmens relativ zu dem Körperabschnitt des Rahmens zu bewirken.

2. Vorrichtung nach Anspruch 1, **dadurch gekennzeichnet, dass** die zu legende Verankerungsvorrichtung einen länglichen Faden mit einem an beiden Enden derselben positionierten Verankerungselement umfasst, und wobei

a) die Griffereinrichtung eine darin gebildete innere Betätigungskammer (632) aufweist zum Unterbringen einer sich hin- und herbewegenden Trägereinrichtung (644);

b) der Nadelkörper hin- und herbewegbar ist und sich von der Trägereinrichtung erstreckt, und die hierdurch sich erstreckende Axialbohrung zum Halten der Ausrichtung der Verankerungselemente dient;

c) das Betätigungsmittel zur anschließenden Vorwärtsbewegung eines der Verankerungselemente von einem distalen Ende des Nadelkörpers dient;

d) ein operativ mit dem Rahmen zusammenhängendes Gelenkkontrollmittel vorgesehen ist zum Bewirken der gelenkigen Bewegung des distalen Endabschnittes des Rahmens relativ zu dem Körperabschnitt des Rahmens; und

f) ein operativ mit dem Rahmen zusammenhängendes Drehkontrollmittel vorgesehen ist zum Bewirken der Drehung des distalen Endabschnittes des Rahmens um eine sich hierdurch erstreckende longitudinale Achse relativ zu dem Körperabschnitt des Rahmens.

3. Vorrichtung nach Anspruch 1 oder 2, wobei

a) das Betätigungsmittel für die anfängliche Bewegung des Nadelkörpers in longitudinaler Richtung relativ zu dem länglichen Rahmen und für die anschließende Vorwärtsbewegung der chirurgischen Verankerungsvorrichtung von einem distalen Ende des Nadelkörpers konfiguriert ist.

4. Vorrichtung nach einem der vorhergehenden Ansprüche, wobei das Betätigungsmittel eine Trägereinrichtung, die für die Hin- und Herbewegung innerhalb einer Betätigungskammer des Gehäuses konfiguriert ist, und einen Kolbenmechanismus (634), der für die Hin- und Herbewegung relativ zur Trägereinrichtung konfiguriert ist, umfasst.

5. Vorrichtung nach Anspruch 4, wobei das Betätigungsmittel des Weiteren eine längliche Zuführstange (654), die operativ mit dem Kolbenmechanismus verbunden ist und sich in die Axialbohrung des Nadelkörpers erstreckt, für die sequentielle Vorwärtsbewegung der Verankerungselemente umfasst.

6. Vorrichtung nach Anspruch 5, des Weiteren umfassend ein Mittel zum Unterbinden der Bewegung der Zuführstange, bis der Kolbenmechanismus einen ersten longitudinalen Abstand zurückgelegt hat.

7. Vorrichtung nach Anspruch 6, wobei das Unterbindungsmittel ein sich drehendes Sperrelement (658) umfasst, das mit der Trägereinrichtung verbunden ist und derart konfiguriert ist, um mit dem Kolbenmechanismus zu interagieren, bis der Kolbenmechanismus diesen ersten longitudinalen Abstand zurückgelegt hat.

8. Vorrichtung nach einem der vorhergehenden Ansprüche, des Weiteren umfassend ein Mittel zum Erlauben der sequentiellen Vorwärtsbewegung des Betätigungsmittels.

9. Vorrichtung nach einem der vorhergehenden Ansprüche in Kombination mit der chirurgischen Verankerungsvorrichtung zum Verankern von Gewebe, wobei die chirurgische Verankerungsvorrichtung umfasst:

a) einen länglichen Faden (12), der gegenüberliegende Endabschnitte bestimmt;

b) ein erstes Verankerungselement (14), das an einem Ende des Fadens positioniert ist, und ein zweites Verankerungselement (16), das an dem gegenüberliegenden Ende des Fadens positioniert ist;

- c) ein Klemmelement (20), das an dem Faden zwischen dem ersten und zweiten Verankerungselement vorgesehen ist und in Bezug auf dieses bewegbar ist zum Annähern des ersten und zweiten Verankerungselements. 5
10. Vorrichtung nach Anspruch 9, wobei das Klemmelement ein Gehäuse, das eine Durchführung zum Aufnehmen zumindest eines Abschnittes des Fadens bestimmt, und ein spitz zulaufendes Keilelement (175), das innerhalb der Durchführung (22) angeordnet ist und wahlweise darin bewegbar ist zum Ermöglichen der relativen Bewegung des Fadens und des Klemmelements, um die operative Länge des Fadens einzustellen, umfasst. 10 15
11. Vorrichtung nach Anspruch 9, wobei das spitz zulaufende Keilelement eine Mehrzahl von sich nach außen erstreckenden Rippen (178, 180) umfasst, die mit dem Faden in Eingriff treten. 20
12. Vorrichtung nach Anspruch 10 oder 11, wobei das Klemmelement des Weiteren ein Mittel (172, 182) umfasst zum Beschränken der relativen Bewegung des Gehäuses und des Keilelements. 25
13. Vorrichtung nach Anspruch 12, wobei das Beschränkungsmittel einen Vorsprung (182), der mit dem Keilelement einen Winkel einschließt, und eine Schiene (172), die in dem Gehäuse bestimmt ist zum Aufnehmen des Vorsprungs, umfasst. 30

#### Revendications 35

1. Appareil (200) pour appliquer un dispositif d'ancrage chirurgical à du tissu corporel comprenant : 35
- a) un ensemble formant poignée (202) définissant un axe longitudinal ; et 40
- b) un corps d'aiguille (204) s'étendant à partir de ladite portion de poignée, ledit corps d'aiguille possédant un perçage axial (214) s'étendant à travers celui-ci pour retenir ledit dispositif d'ancrage chirurgical ; l'appareil étant caractérisé par : 45
- c) un châssis oblong s'étendant distalement à partir dudit ensemble formant poignée et comportant une portion de corps et une portion d'extrémité distale conçue pour un mouvement articulé, ladite portion d'extrémité distale possédant un orifice de réception de tissu (628), défini dans celle-ci ; 50
- d) ledit corps d'aiguille s'étendant à travers ladite portion de corps, audit orifice de réception de tissu ; 55
- e) un moyen d'actionnement (208) fonctionnellement associé audit ensemble formant poi-

gnée pour déplacer initialement ledit corps d'aiguille relativement audit châssis pour communiquer avec ledit orifice d'engagement de tissu et pour faire avancer ensuite ledit élément d'ancrage à partir d'une extrémité distale dudit corps d'aiguille ; et

f) un moyen de commande fonctionnellement associé audit châssis pour effectuer un mouvement articulé de ladite portion d'extrémité distale dudit châssis relativement à ladite portion de corps dudit châssis.

2. Appareil selon la revendication 1, où ledit dispositif d'ancrage à appliquer comprend un fil de suture oblong ayant un élément d'ancrage positionné à chaque extrémité de celui-ci, et où

a) l'ensemble de poignée possède une chambre d'actionnement interne (632) formée dans celui-ci pour loger un ensemble porteur (644) à mouvement alternatif ;

b) le corps d'aiguille est apte à exécuter un mouvement alternatif et s'étend depuis ledit ensemble porteur, et le perçage axial s'étendant à travers celui-ci est destiné à maintenir lesdits éléments d'ancrage en alignement ;

c) le moyen d'actionnement est prévu pour faire avancer ensuite l'un desdits éléments d'ancrage à partir d'une extrémité distale dudit corps d'aiguille ;

d) un moyen de commande d'articulation associé fonctionnellement audit châssis est prévu pour effectuer un mouvement articulé de ladite portion d'extrémité distale dudit châssis relativement à ladite portion de corps dudit châssis ; et

e) un moyen de commande de rotation fonctionnellement associé audit châssis est prévu pour effectuer la rotation de ladite portion d'extrémité distale dudit châssis autour d'un axe longitudinal s'étendant à travers celui-ci relativement à ladite portion de corps dudit châssis.

3. Appareil selon la revendication 1 ou 2, où

a) le moyen d'actionnement est configuré pour déplacer initialement ledit corps d'aiguille dans une direction longitudinale relativement audit châssis oblong et pour faire avancer ensuite ledit dispositif d'ancrage chirurgical d'une extrémité distale dudit corps d'aiguille.

4. Appareil selon l'une des revendications précédentes, où ledit moyen d'actionnement comprend un ensemble porteur configuré en vue d'un mouvement de va-et-vient dans une chambre d'actionnement dudit boîtier ainsi qu'un mécanisme plongeur (634) configuré en vue d'un mouvement de va-et-

vient relativement audit ensemble porteur.

5. Appareil selon la revendication 4, où ledit moyen d'actionnement comprend en outre une tige d'amenée oblongue (654) fonctionnellement reliée audit mécanisme plongeur et s'étendant dans le perçage axial dudit corps d'aiguille pour faire avancer séquentiellement lesdits éléments d'ancrage à partir de celui-ci. 5
6. Appareil selon la revendication 5, comprenant en outre un moyen pour empêcher un mouvement de ladite tige d'amenée jusqu'à ce que ledit mécanisme plongeur ait parcouru ladite première distance longitudinale. 10 15
7. Appareil selon la revendication 6, où ledit moyen d'inhibition comprend un élément de loquet pivotant (658) relié audit ensemble porteur et configuré en vue d'une interaction avec ledit mécanisme plongeur jusqu'à ce que ledit mécanisme plongeur ait parcouru ladite première distance longitudinale. 20
8. Appareil selon l'une des revendications précédentes, comprenant en outre un moyen pour permettre l'avance séquentielle dudit moyen d'actionnement. 25
9. Appareil selon l'une des revendications précédentes en combinaison avec ledit dispositif d'ancrage chirurgical pour l'ancrage du tissu, où ledit dispositif d'ancrage chirurgical comprend : 30
  - a) un fil de suture oblong (12) définissant des portions d'extrémité opposées ;
  - b) un premier élément d'ancrage (14) positionné à une extrémité dudit fil de suture et un second élément d'ancrage (16) positionné à l'extrémité opposée dudit fil de suture ; 35
  - c) un élément de serrage (20) prévu sur ledit fil de suture entre lesdits premier et second éléments d'ancrage et déplaçable par rapport à ceux-ci pour rapprocher lesdits premier et second éléments d'ancrage. 40
10. Appareil selon la revendication 9, où ledit élément de serrage comprend un boîtier définissant un passage pour recevoir au moins une portion dudit fil de suture et un élément de coin rétréci (175) disposé dans ledit passage (22) et déplaçable sélectivement dans celui-ci pour permettre un mouvement relatif dudit fil de suture et dudit élément de serrage pour ajuster la longueur fonctionnelle dudit fil de suture. 45 50
11. Appareil selon la revendication 9, où ledit élément de coin rétréci comprend plusieurs nervures (178, 180) s'étendant vers l'extérieur pour la mise en prise avec ledit fil de suture. 55

12. Appareil selon la revendication 10 ou 11, où ledit élément de serrage comprend en outre un moyen (172, 182) pour limiter un déplacement relatif dudit boîtier et dudit élément de coin.

13. Appareil selon la revendication 12, où ledit moyen de limitation comprend une protubérance (182) qui s'étend vers le bas à partir dudit élément de coin ainsi qu'un chemin (172) défini dans ledit boîtier pour recevoir ladite protubérance.

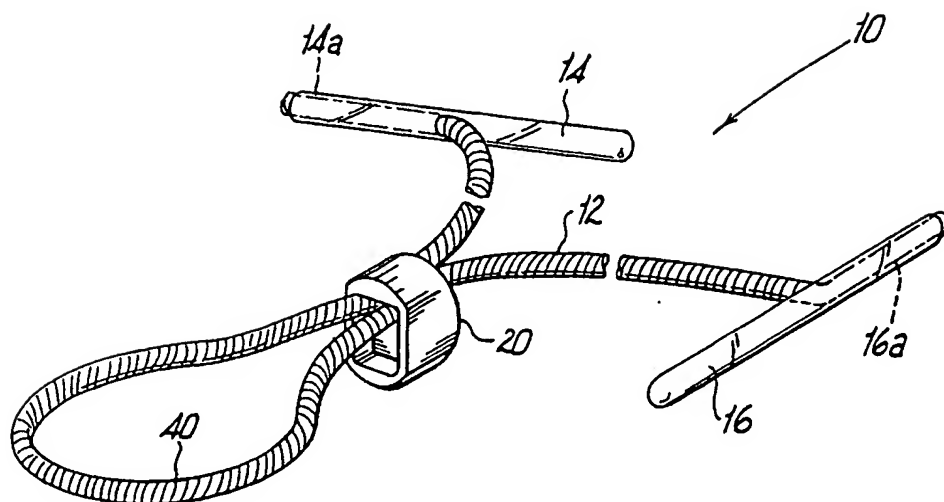


FIG. 1

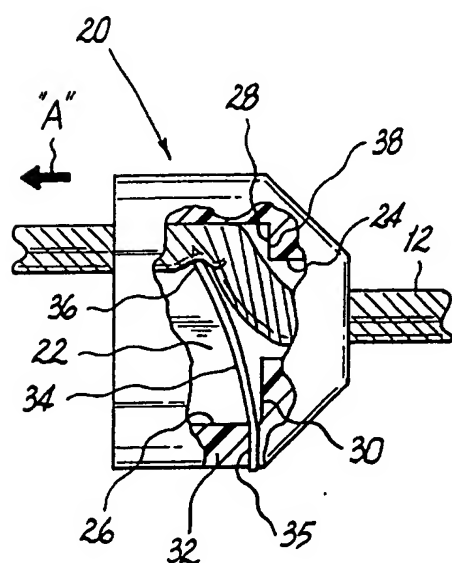


FIG.2

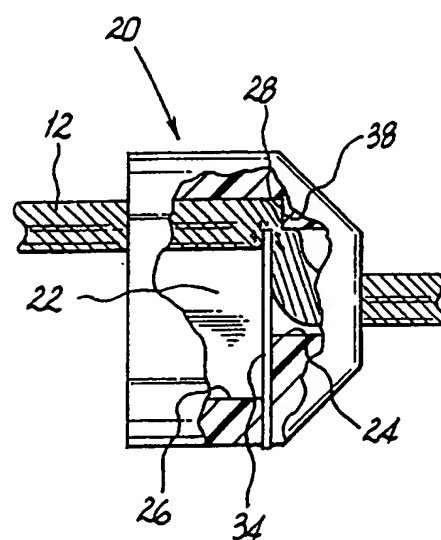


FIG. 3



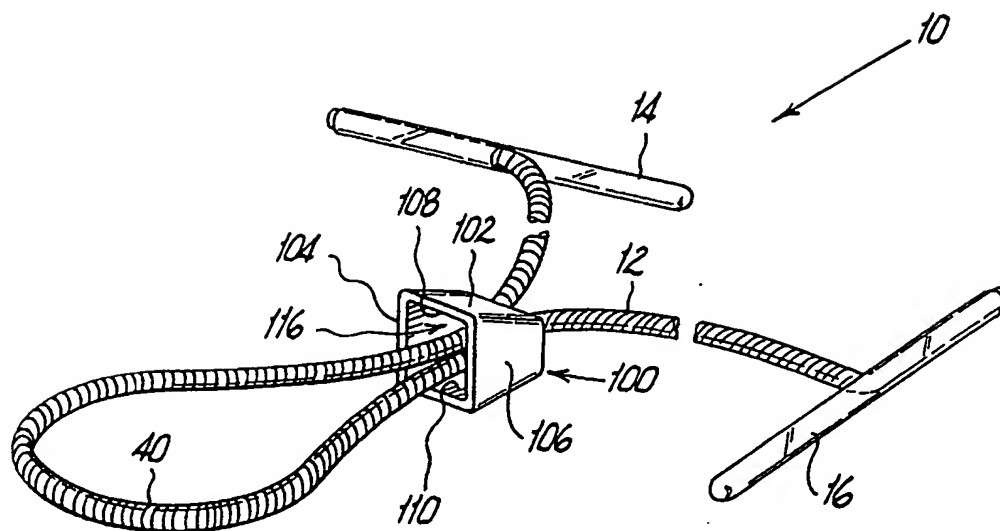


FIG. 4

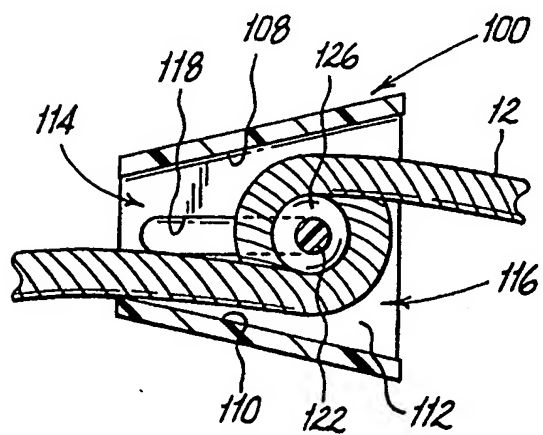


FIG. 5A

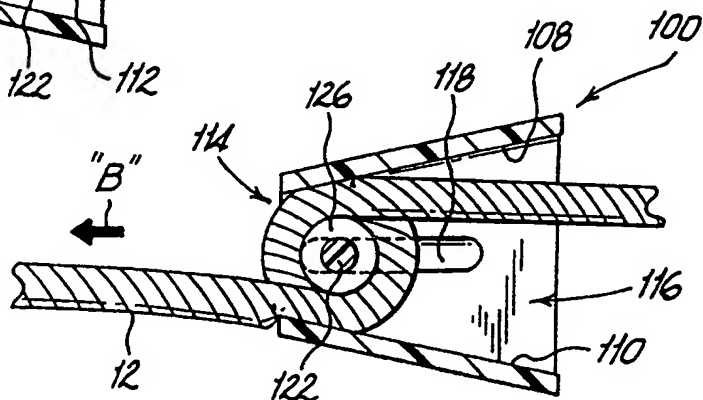
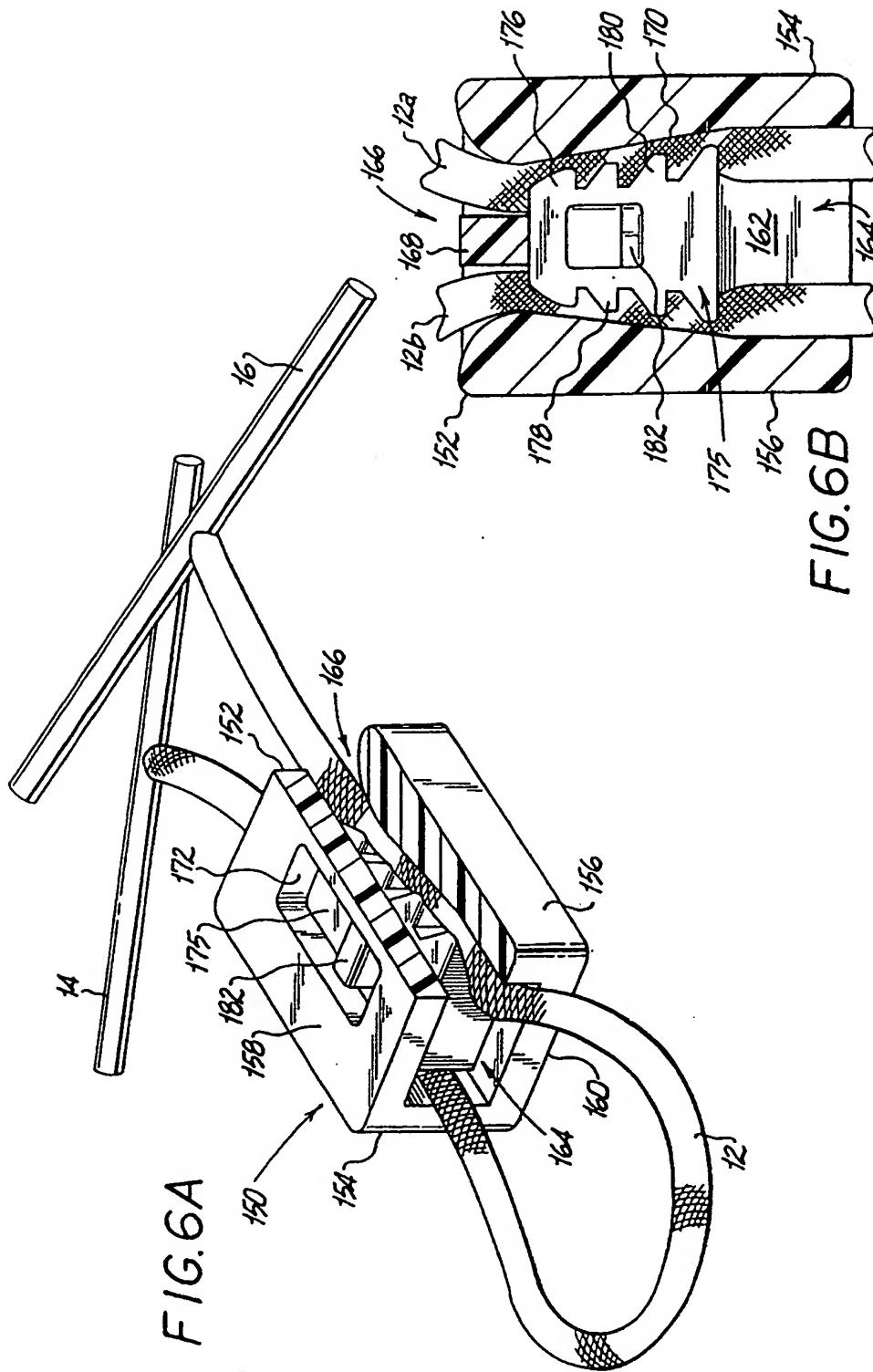
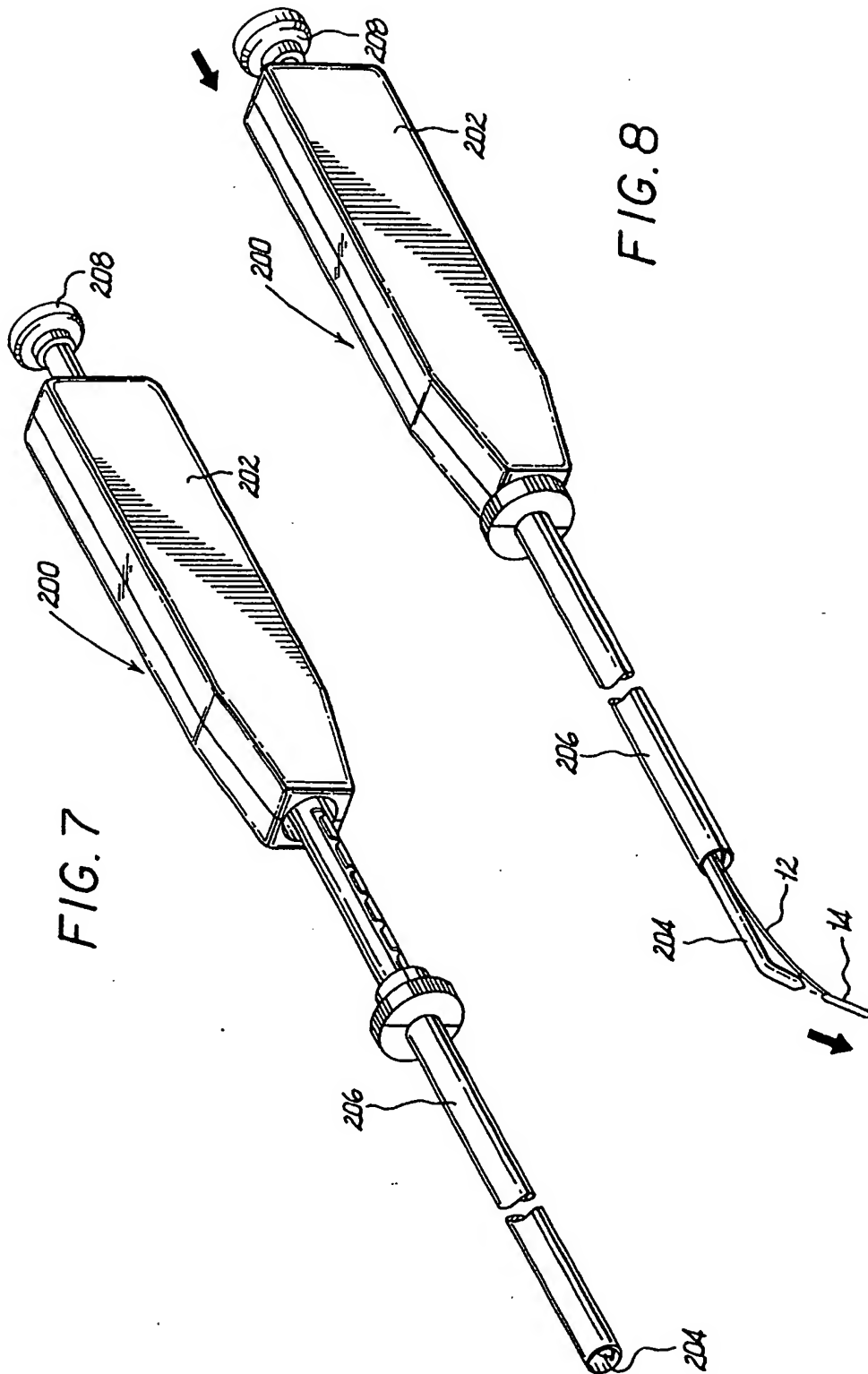
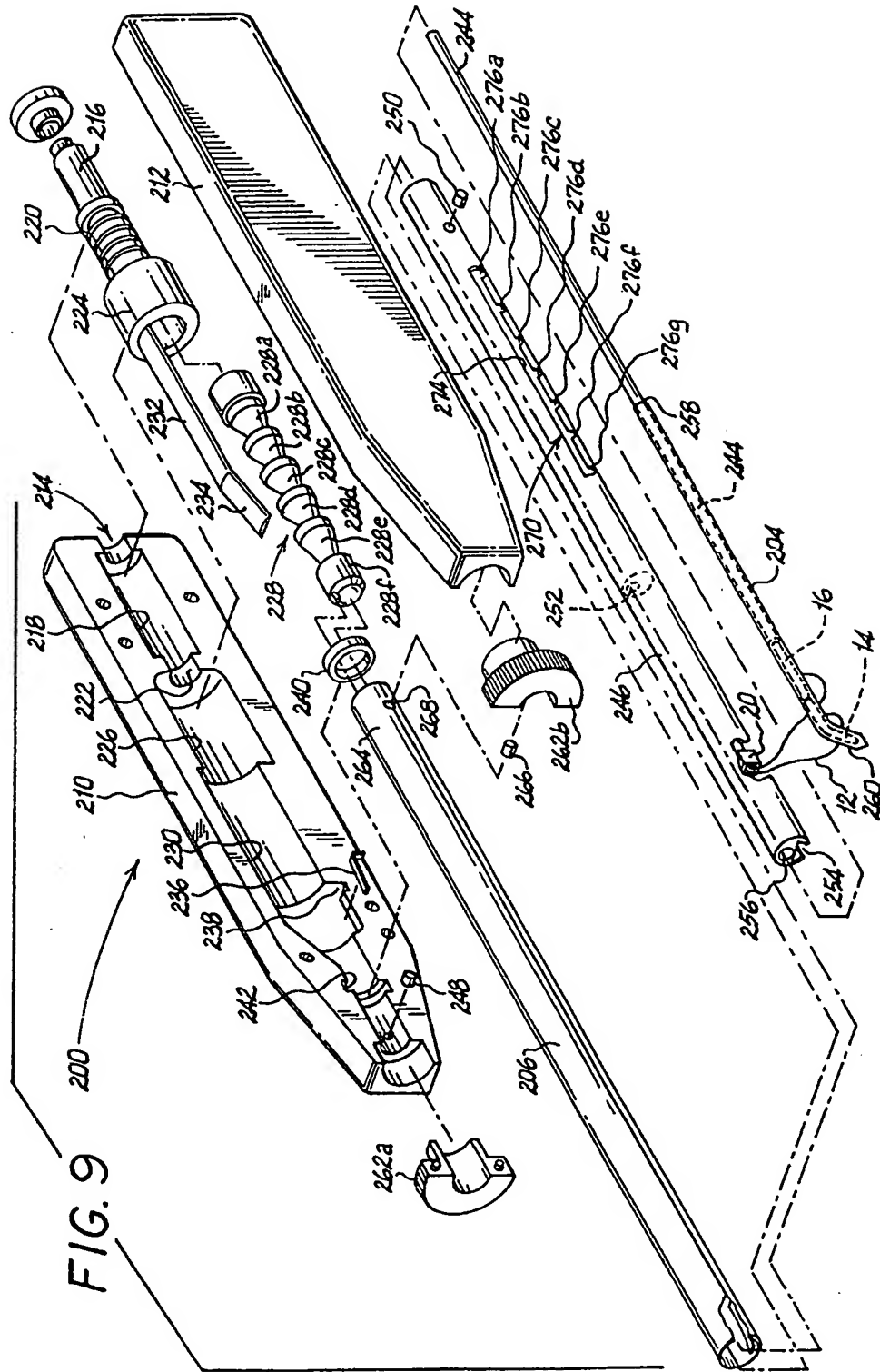


FIG. 5B







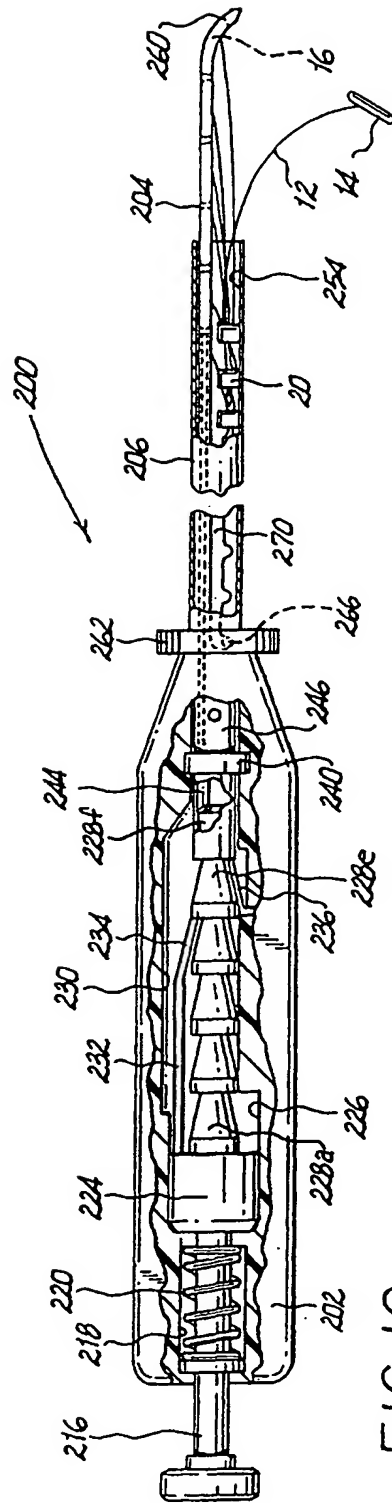


FIG. 10

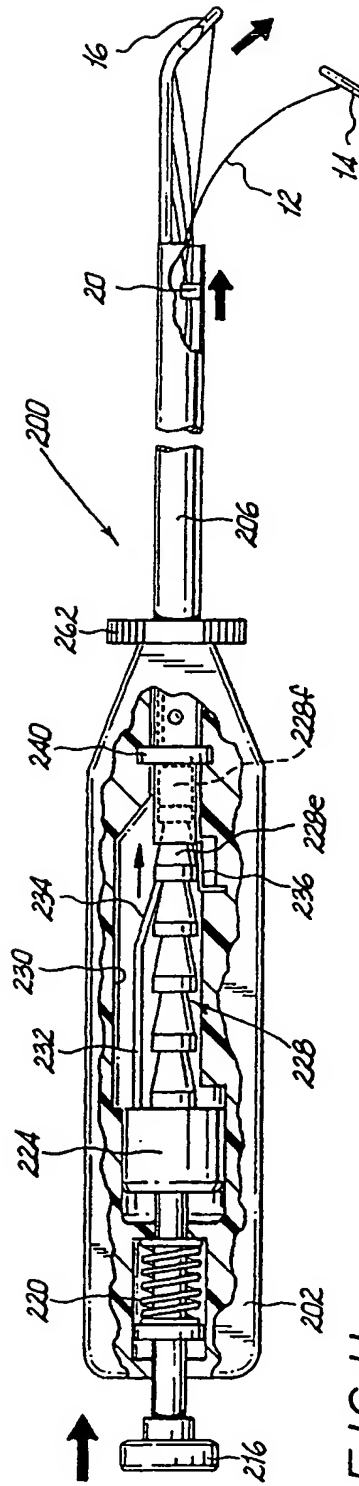


FIG. 11

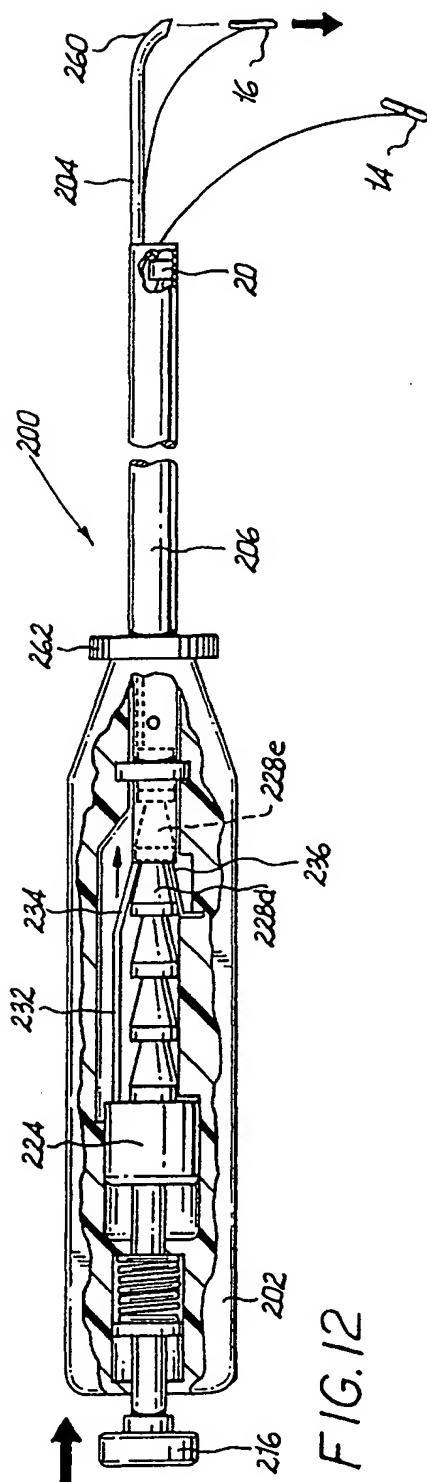


FIG. 12

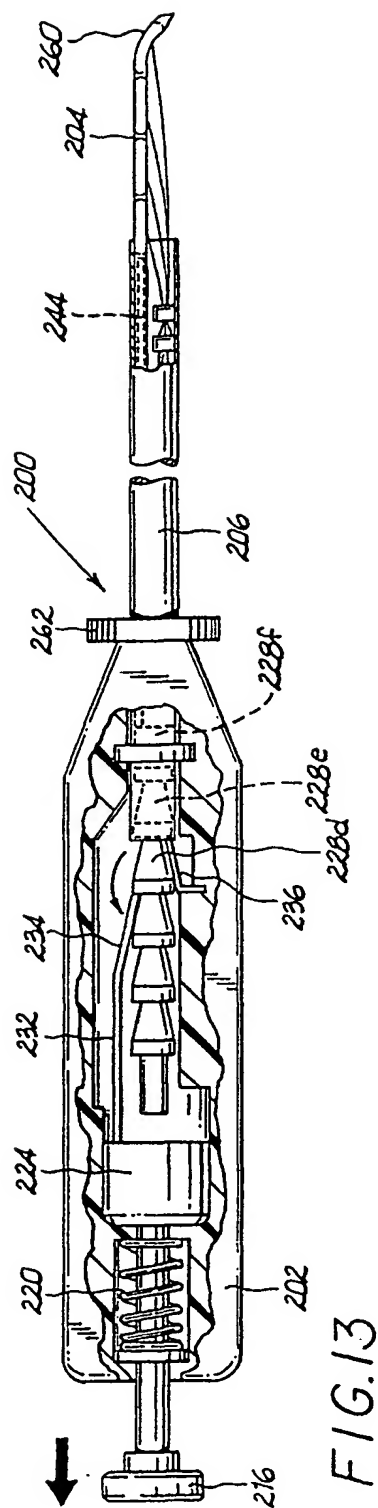


FIG. 13

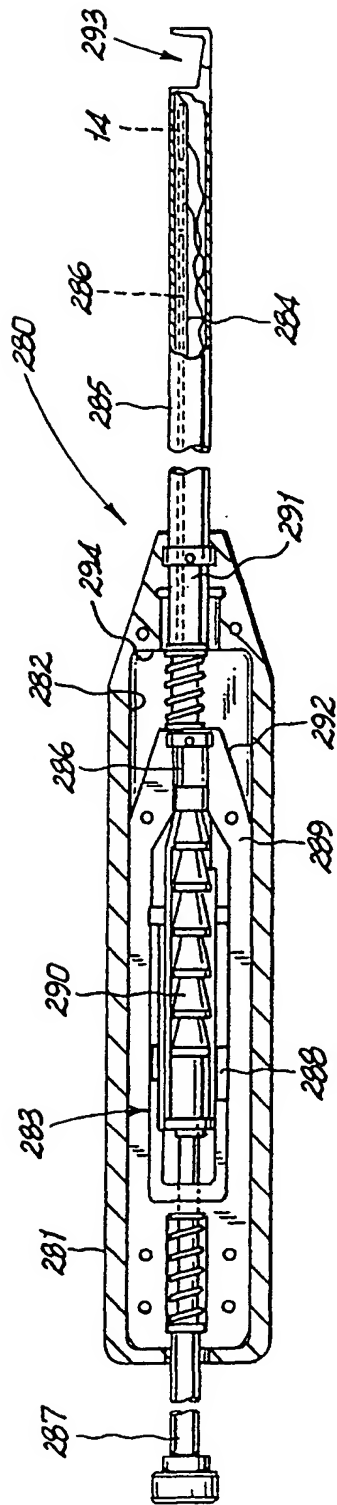


FIG. 14A

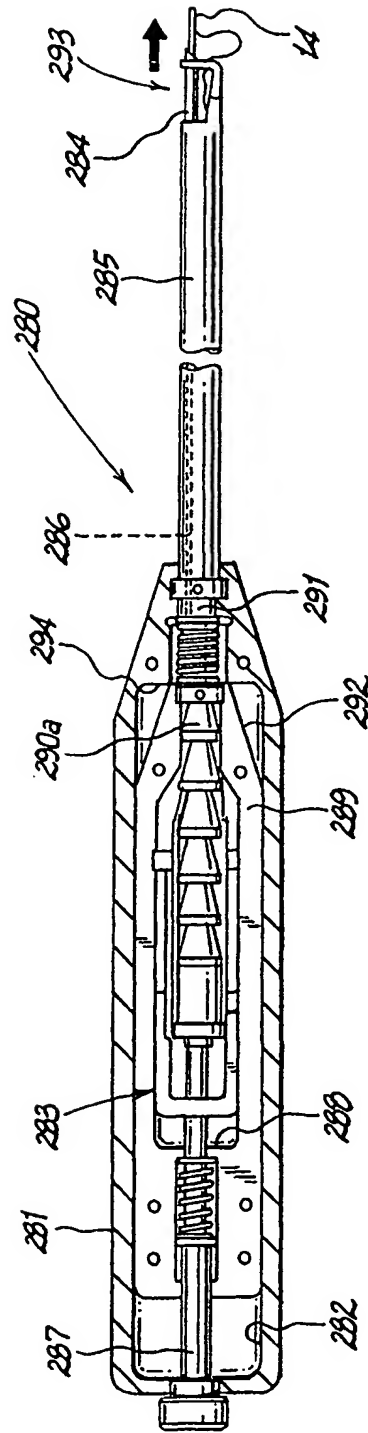
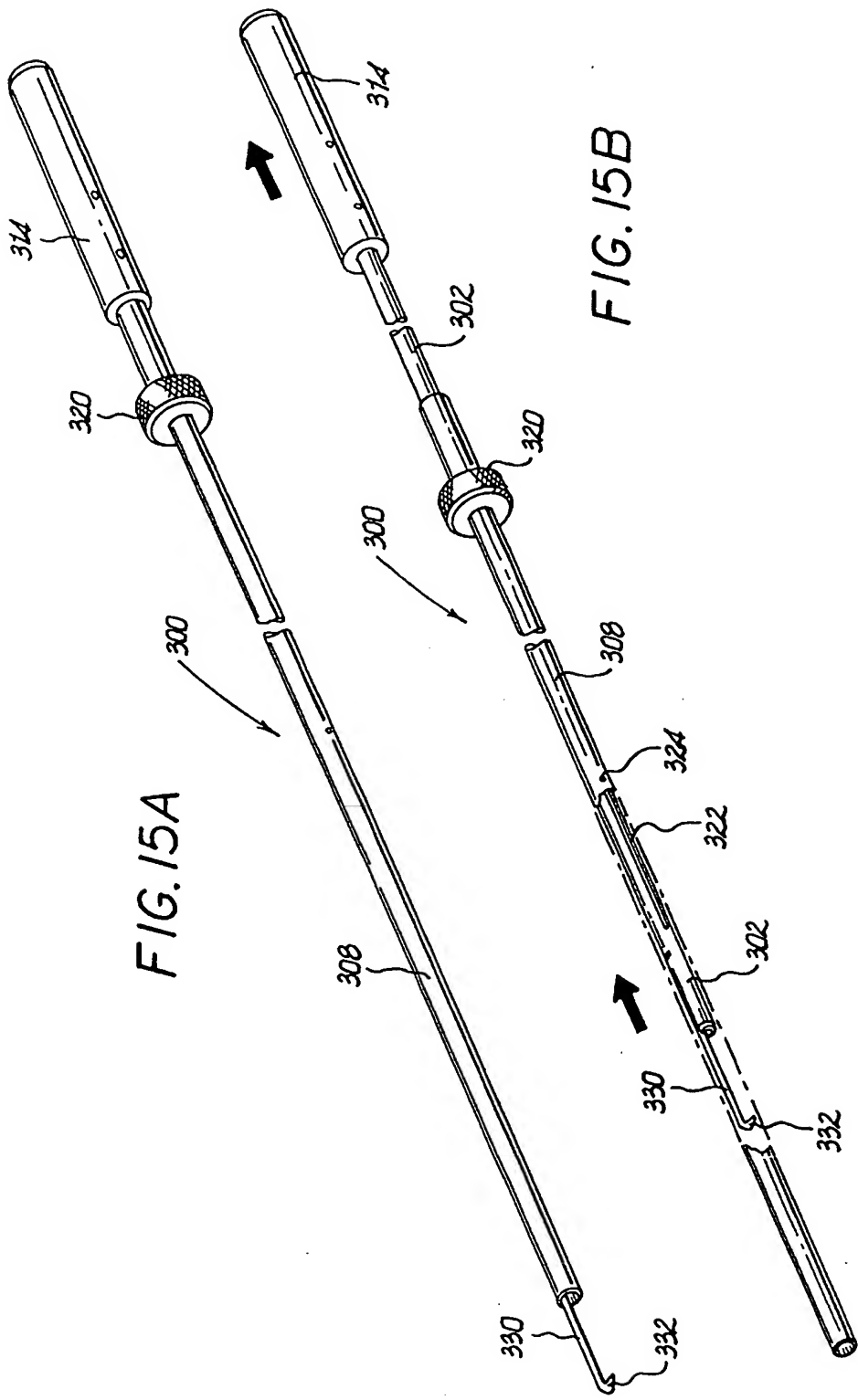
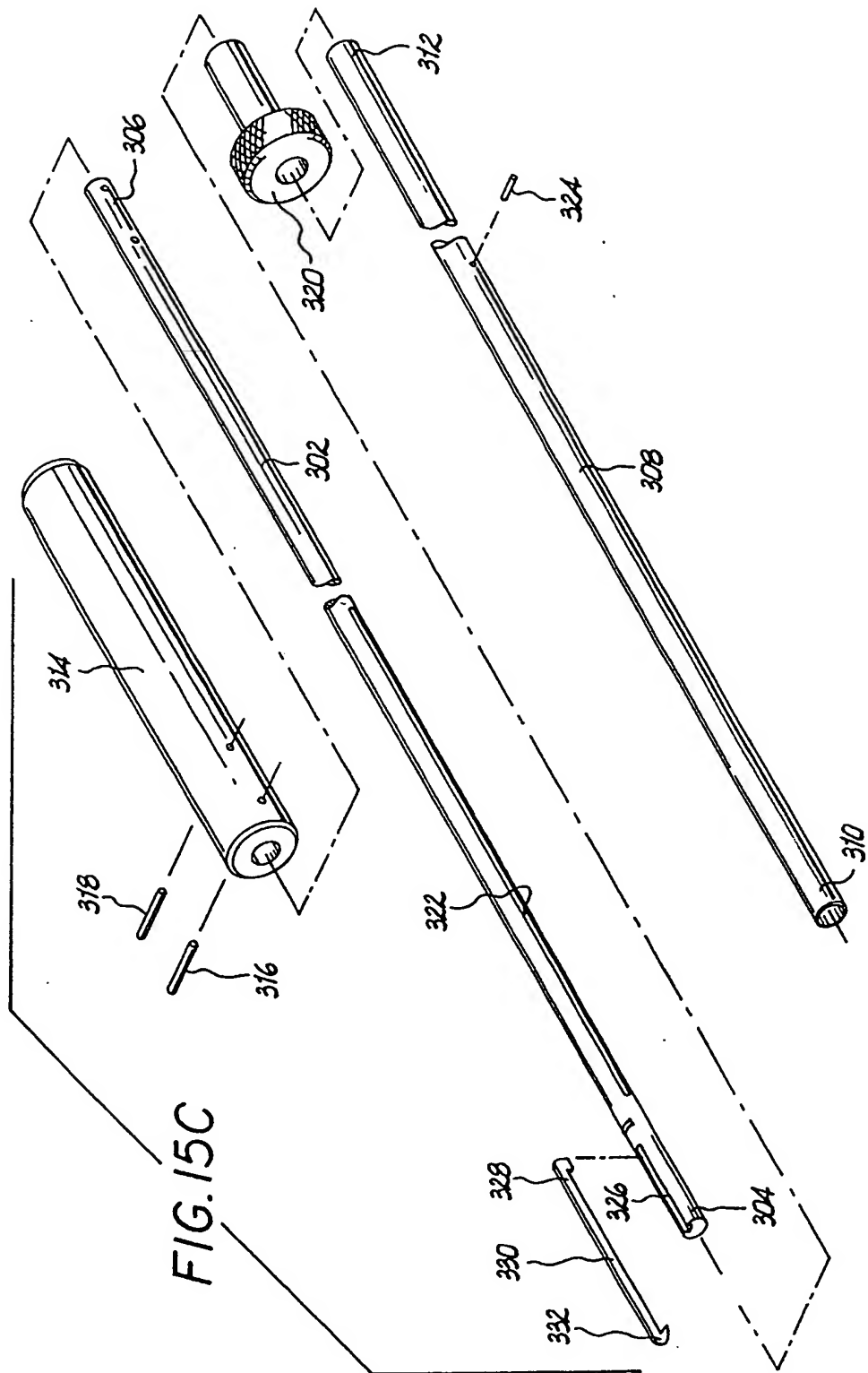
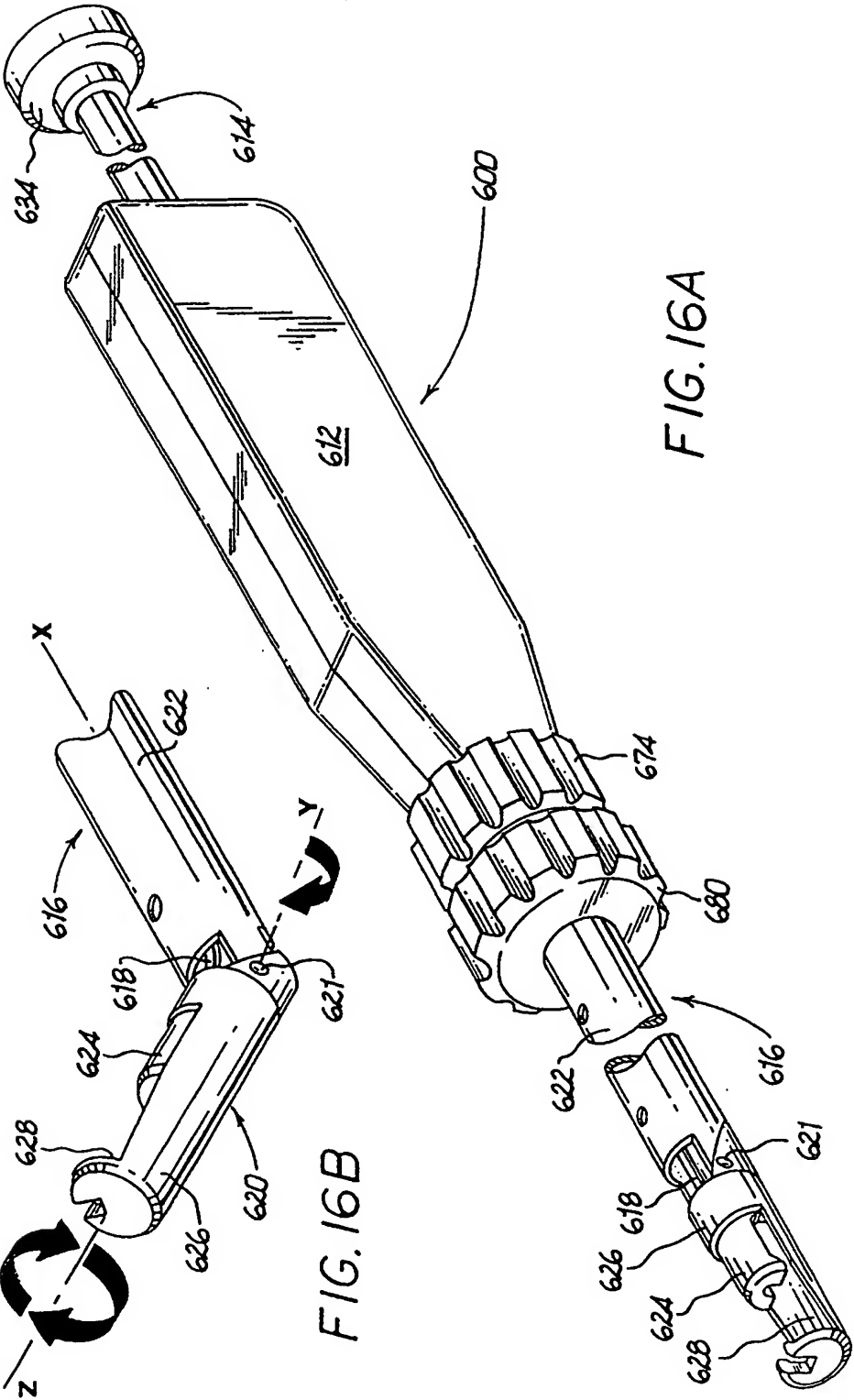


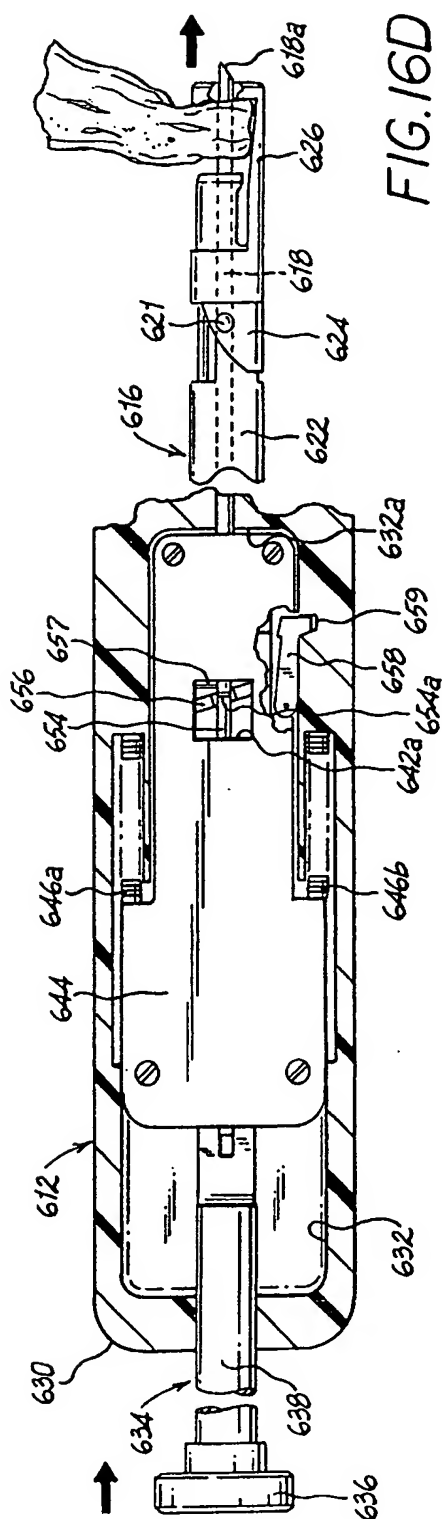
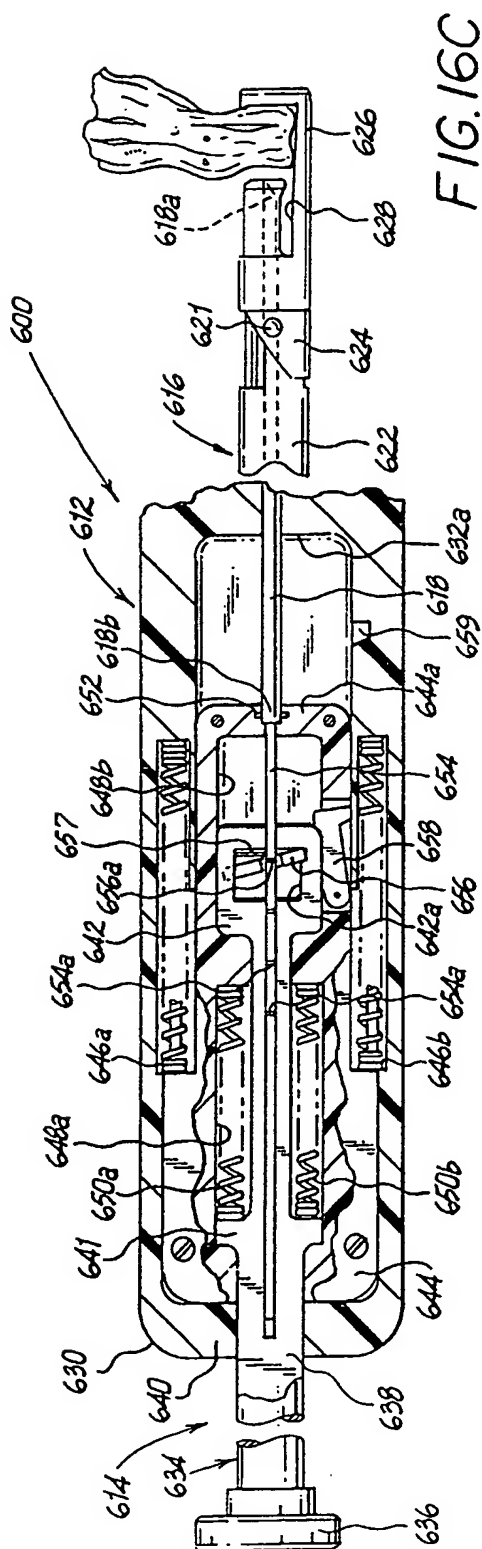
FIG. 14B











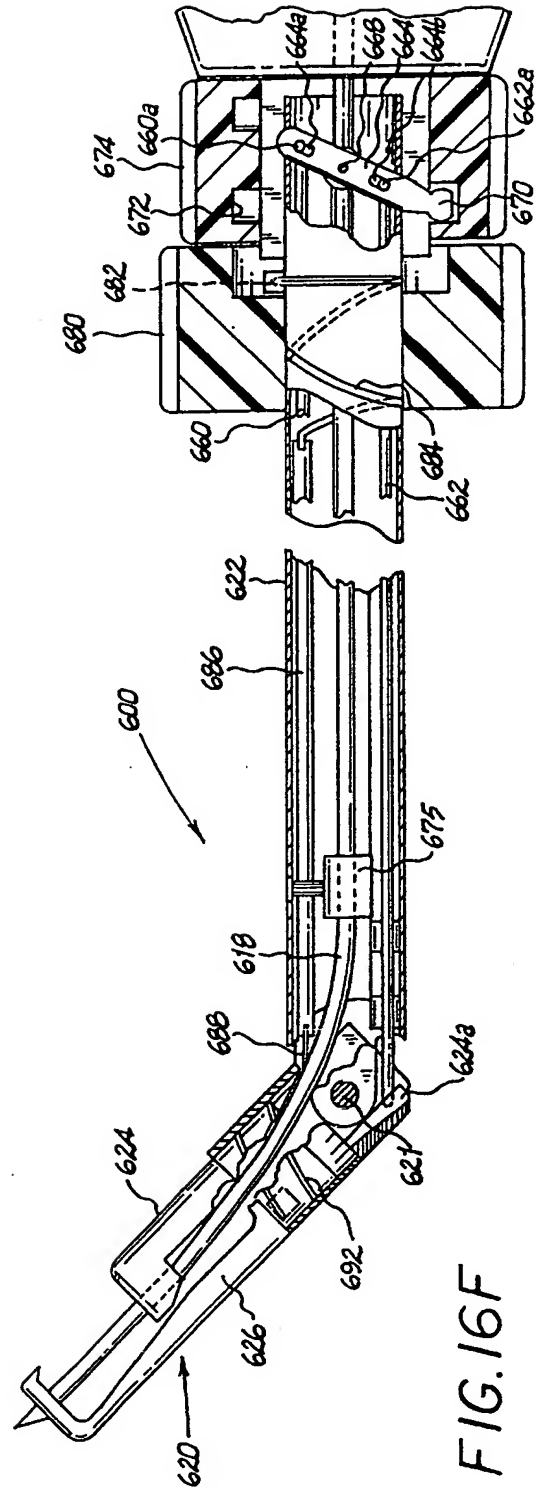
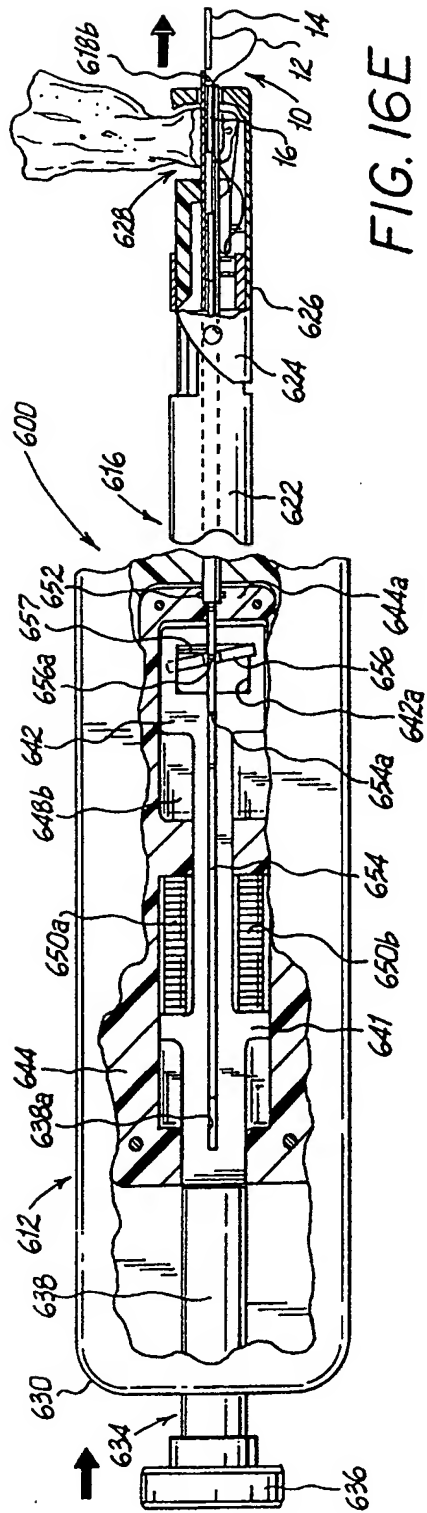


FIG. 17

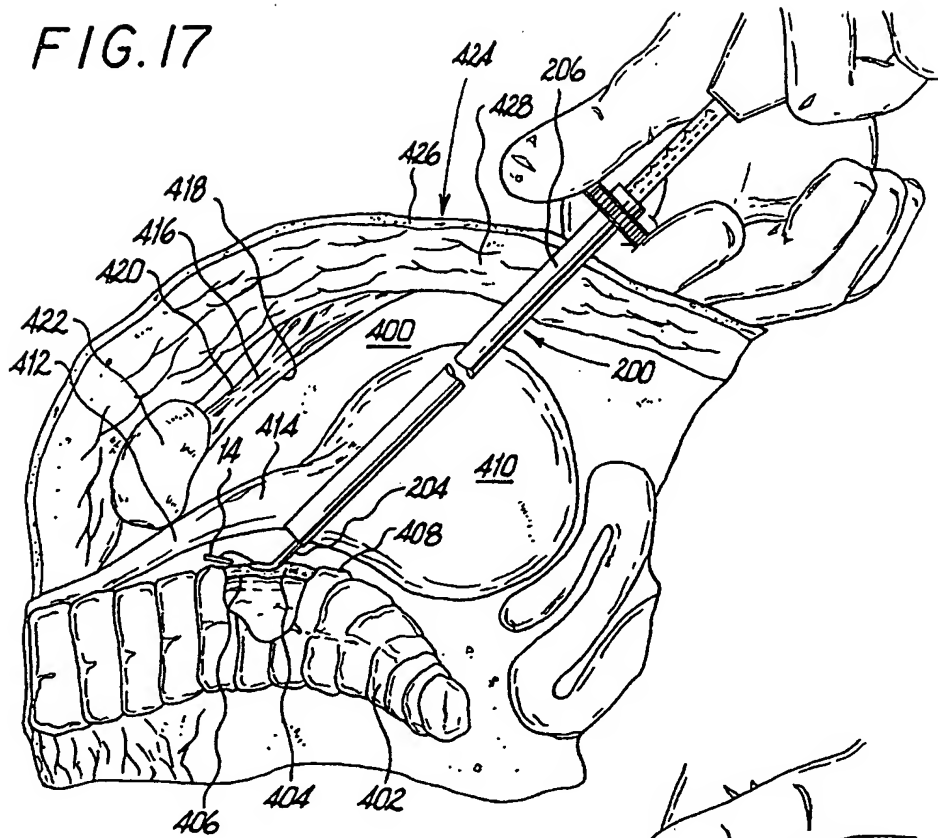
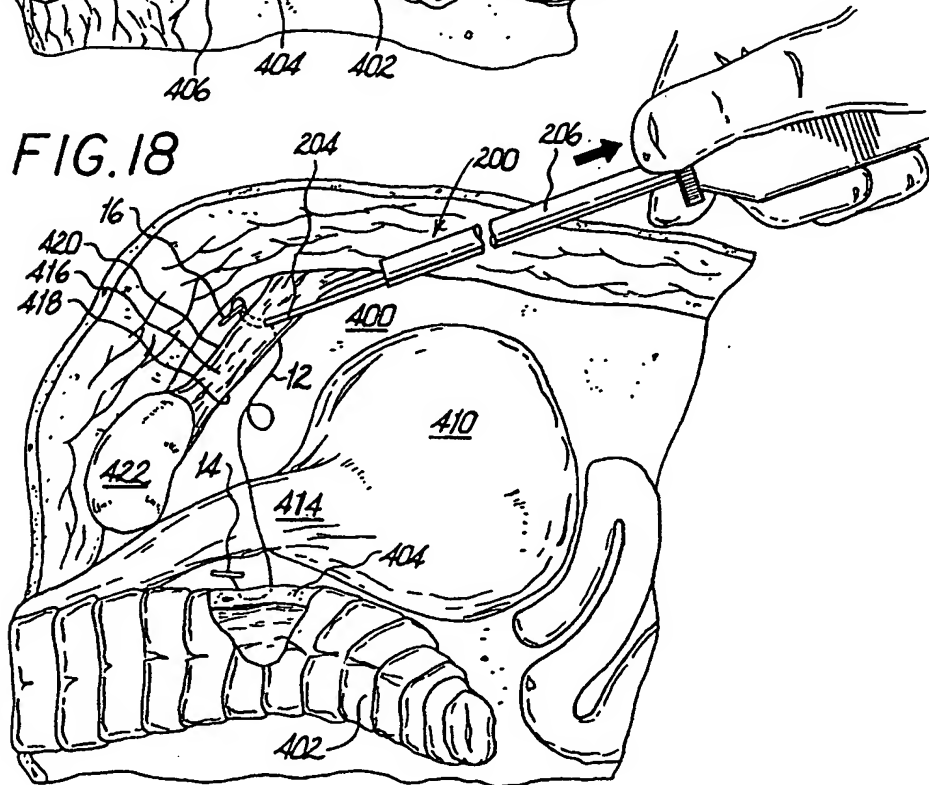


FIG. 18



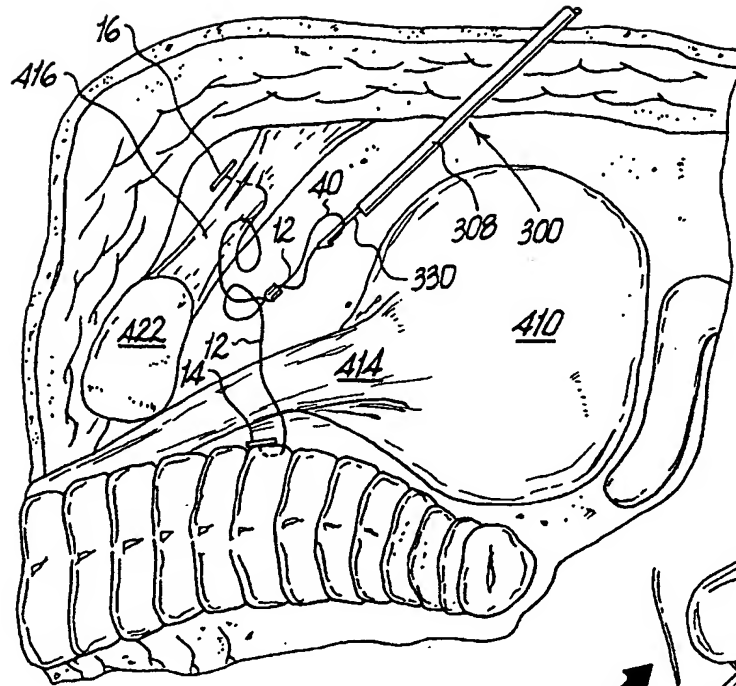


FIG. 19

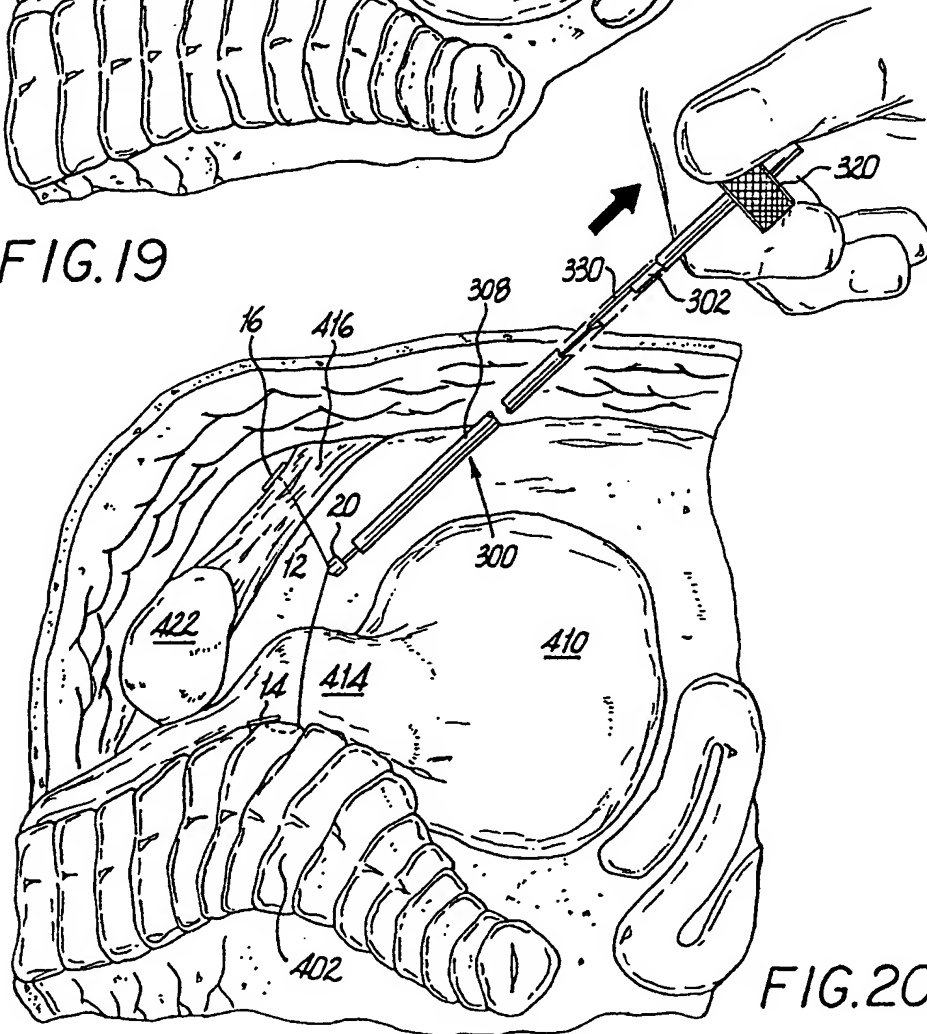


FIG. 20

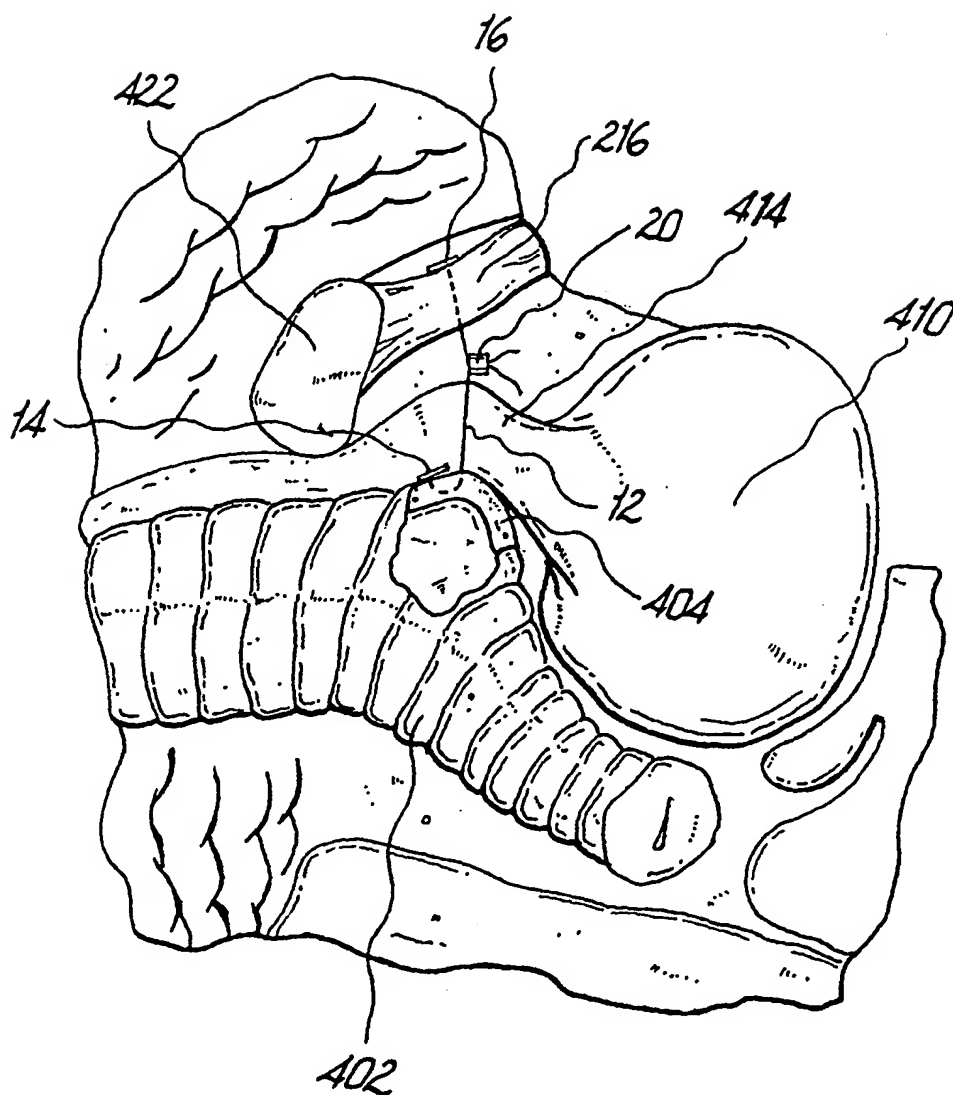


FIG. 21

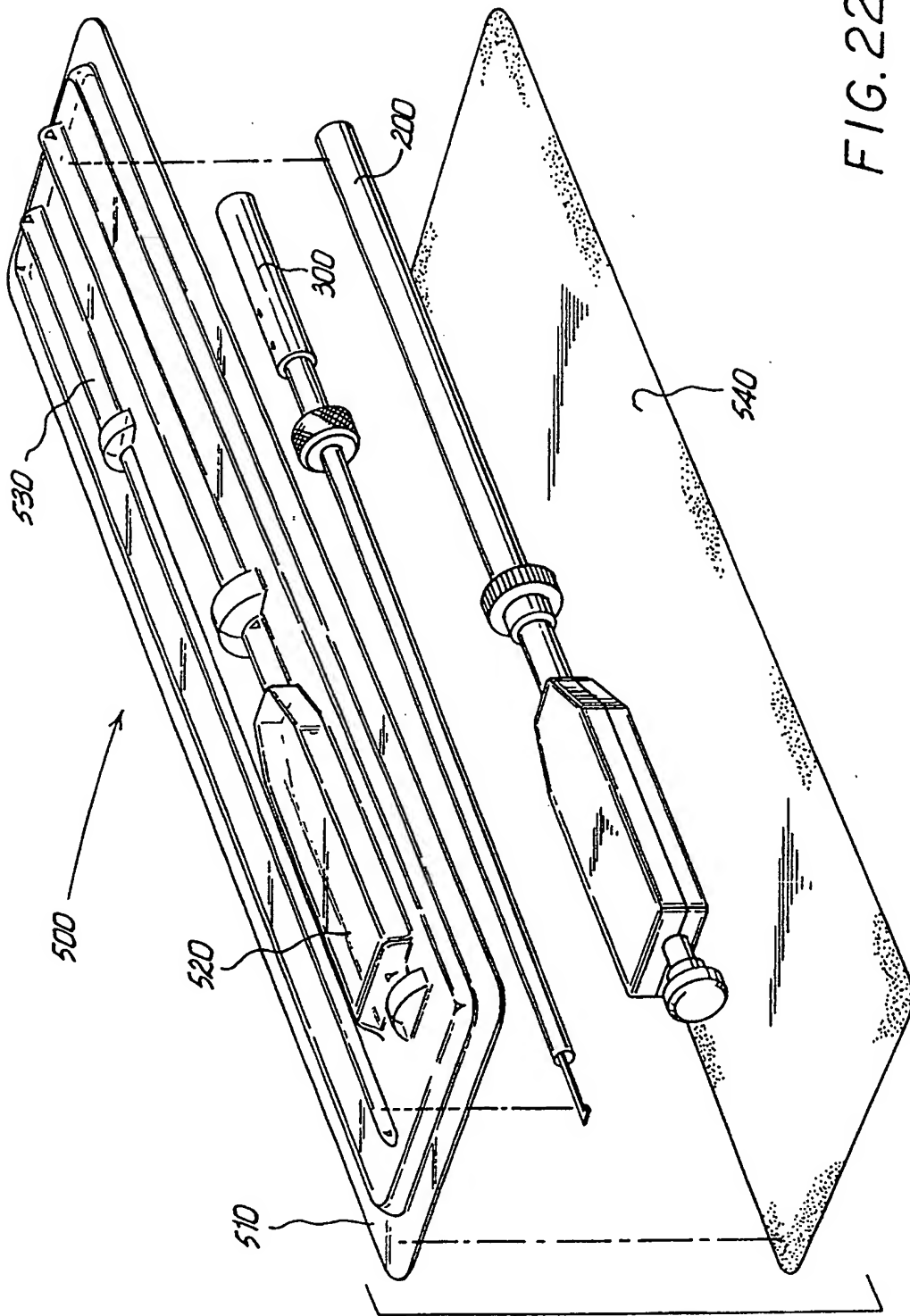


FIG. 22